

Galaxy Bias

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- One problem when interpreting galaxy surveys is that galaxies might be a "biased" realization of the DM field.
- Typically one assumes

$$\delta_g = b \delta(\vec{x}) \quad \leftarrow \text{overdensities are proportional.}$$

$$\downarrow$$
$$P_g = b^2 P(k)$$

- This might be valid on large Gaussian scales but NOT when non-gaussianities start to kick in.
- One would think that for any given cosmological model a hydrodynamical simulation could tell us the relation $g \leftrightarrow m$. But the process of galaxy formation is far from being understood so one needs to introduce phenomenological parameters \rightarrow "bias parameters".
- 3 ways forward
 - \rightarrow hydro simulations (costly / unknown physics)
 - \rightarrow mapping of $\delta_m \rightarrow \delta_g$ (bias parameters)
 - \rightarrow let dark-matter collapse into halos which is a gravitational problem; place galaxies into those halos w/ some assumptions to avoid complex gal. formation physics.

Clustering of tracers

• It's being known for a long time that the clustering of objects such as galaxies of different types, clusters, etc vary \Rightarrow ~~so~~ it depends on the object \Rightarrow clustering is not universal and it's not ~~directly~~ directly the same as DM. \Rightarrow this is called "bias"

Simplest model is "local bias"

Let's assume we smooth both the DM and tracer field on some scale such that fluctuations are small \Rightarrow local bias assumption

$$\delta_g(\vec{x}) = f \{ \delta(\vec{x}) \} \quad \Leftarrow \text{Eq (*)}$$

Since fluctuations are small we can Taylor expand

$$\delta_g = \sum_{k=0}^{\infty} \frac{b_k}{k!} \delta^k = b_1 \delta + \frac{b_2}{2} (\delta^2 - \sigma^2)$$

\uparrow such that $\langle \delta_g \rangle = 0$

We can then calculate

$$\langle \sigma_g^2 \rangle = b_1^2 \langle \sigma^2 \rangle$$

$$\langle \delta_g^3 \rangle = b_1^3 \langle \delta^3 \rangle + \frac{b_2}{2} 3b_1^2 \langle (\delta^2 - \sigma^2) \delta^2 \rangle$$

$$\downarrow$$
$$3\sigma^4 - \sigma^4 = 2\sigma^4$$

\uparrow all possible combinations of $\langle \delta\delta\delta\delta \rangle$

$$\langle \delta_g^3 \rangle = b_1^3 \langle \delta^3 \rangle + 3b_1^2 b_2 \sigma^4$$

$$S_{3g} = \frac{b_1^3 \langle \delta^3 \rangle + 3b_2 b_1^2 \sigma^4}{b_1^4 \sigma^4} = \frac{1}{b_1} S_3 + 3 \frac{b_2}{b_1^2}$$

or in Fourier Space

$$P_g(k) \approx b_1^2 P(k)$$

$$B_g(k_1, k_2, k_3) = b_1^3 B(k_1, k_2, k_3) + \frac{b_2}{b_1^2} \{ P(k_1)P(k_2) + \text{cyc} \}$$

$$Q_g(\vec{k}_1, \vec{k}_2, \vec{k}_3) = \frac{1}{b_1} Q(k_1, k_2, k_3) + \frac{b_2}{b_1^2}$$

The last expression shows how ~~can~~ one can measure bias \Rightarrow

Measure Q_g ; predict Q (matter) \Rightarrow this is independent of σ_8 !

Measure b_1, b_2 .

Otherwise note that $P_g(k) = b_1^2 P(k) \sim b_1^2 \sigma_8^2 P(k, z=0)$

\downarrow
but $P \sim D^2$ growth factor

or in other words σ_8

\Rightarrow Perfect degeneracy between b_1 and σ_8 .

Eq(*) assumes not only that bias is local but also deterministic

In practice, it is likely that ~~local~~ galaxy formation depends on ~~local~~

variables other than density (e.g. halo formation time)

So

$$\hat{\delta}_g(\vec{x}) = \mathcal{G}\{\delta(\vec{x})\} + \epsilon_\delta(\vec{x})$$

Stochasticity

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such that $\langle \delta \epsilon \rangle = 0$

In general one measures the cross-correlation coefficient

$$\delta_g = b_1 \delta + \epsilon \quad \text{and} \quad \delta$$

$$r = \frac{\langle \delta_g \delta_m \rangle}{\sqrt{\langle \delta_g \delta_g \rangle \langle \delta_m \delta_m \rangle}} = \frac{b_1 \delta^2}{\sqrt{(b_1^2 \delta^2 + \epsilon^2) \delta^2}} = \frac{1}{\sqrt{1 + P_\epsilon / P_{\delta\delta}}}$$

On large scale $r \rightarrow 1$ typically ~~not~~ ($r < 1$ in general). For the combination of WL and Clustering we need $r = 1$.

Limits of local bias picture: Lets assume that at time t_* galaxies do follow local bias \Rightarrow what happens in the future?

In order to solve this let's think on the ^{man} constituent of a galaxy and trace it's center of mass so number of objects is conserved.

$$\left\{ \begin{matrix} \delta \\ x \\ g \end{matrix} \right\} \rightarrow \left\{ \begin{matrix} \delta \\ x \\ g \end{matrix} \right\} \rightarrow \dots \rightarrow \text{⊙}$$

Follow $x \Rightarrow$

$$\frac{\partial \delta_g}{\partial z} + \vec{v} \cdot \{(1 + \delta_g) \vec{v}_g\} = 0$$

Let's further assume that

$\rightarrow v_g = v_m$ since by Galilean Invariance

this has to be the case at least for large scales.

\rightarrow Under these conditions one can show

$$b_1 = 1 + \frac{b_1^* - 1}{D/D_*}$$

So \rightarrow local bias is preserved on linear scales. At 2nd order

this is not true anymore. Gravity generates non-local terms

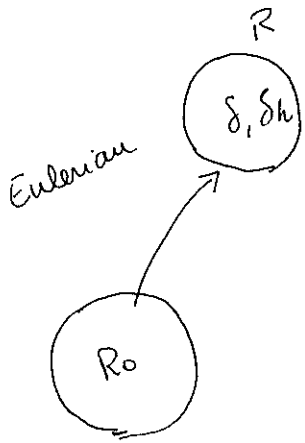
$$\delta g(x) = \int d^3x' \{ \delta(x') \} \kappa(\vec{x} - \vec{x}') d^3x$$

\downarrow \downarrow
non-linear non-local

Halo bias

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We are interested in the following problem



Region of comoving size R

with some enclosed δ overdensity

(nonlinear). This originated from some

fluctuation at original comoving volume R_0

(recall from spherical collapse $R = \frac{R_0}{\sqrt{2\delta}} (1+\delta)^{-1}$)

the comoving size shrinks for $\delta > 0$).

This region will have some overdensity of halos

δ_h that we want to relate to δ .

$$\frac{M}{V_\delta} = \bar{\rho} (1+\delta)$$

We want $\mathcal{N}(m|\delta) dm$: number of halos given the region is overdense. Recall the ^{"standard"} Press - Schechter formalism at $\delta=0$

$F(>M) = 2 \mathcal{P}(\delta_m > \delta_c)$: fraction of mass in halos more massive than m .

$\frac{\partial F(>m)}{\partial m} dm$: fraction of mass in halos $\{m, m+\delta m\}$.

$$\left(\begin{array}{l} \text{number of} \\ \text{halos with } > m \end{array} \right) \times \frac{m}{M} = \frac{\partial F(>m)}{\partial m} dm$$

\swarrow halo mass
 \nwarrow total enclosed mass

$W(m) dm = \# \text{ of halos in the general case}$

$$W(m) dm = \frac{M}{m} \frac{\partial F(>m)}{\partial \sigma^2} \frac{\partial \sigma^2}{\partial m} dm$$

If we divide by the enclosed volume we get the standard mass function (i.e. # of halos per unit volume and mass)

$$n(m) dm = \frac{\bar{\rho}}{m} \frac{\partial F(>m)}{\partial \sigma^2} \frac{\partial \sigma^2}{\partial m} dm.$$

where since we are doing the standard case $\frac{M}{V} \equiv \bar{\rho}$

$$\frac{\partial F(>m)}{\partial \sigma} = 2 \frac{\partial}{\partial \sigma} \mathcal{P}(\delta_m > \delta_c) = \frac{2}{2} \frac{\partial}{\partial \sigma} \text{Erfc} \left(\frac{\delta_c}{\sqrt{2} \sigma} \right)$$

$$= \frac{-2}{\sqrt{\pi}} e^{-\delta_c^2 / 2\sigma^2} \left(\frac{-\delta_c}{\sqrt{2} \sigma^2} \right) = \sqrt{\frac{2}{\pi}} e^{-\delta_c^2 / 2\sigma^2} \frac{\delta_c}{\sigma^2}$$

$$n(m) dm = \frac{\bar{\rho}}{m} \sqrt{\frac{2}{\pi}} e^{-\delta_c^2 / 2\sigma^2} \frac{\delta_c}{\sigma^2} \left| \frac{\partial \sigma}{\partial m} \right| dm$$

$$= \frac{\bar{\rho}}{m} \sqrt{\frac{1}{\pi 2}} e^{-\delta_c^2 / 2\sigma^2} \frac{\delta_c}{\sigma^3} \left| \frac{\partial \sigma^2}{\partial m} \right| dm$$

$$\underbrace{\hspace{10em}}_{\mathcal{F}(v)}$$

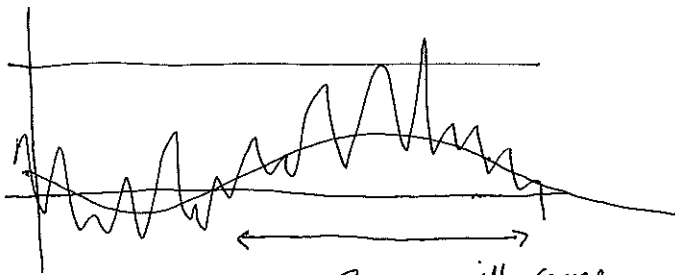
The extension to the conditional mass fraction can be done easily either using

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$$f(\sigma, \delta_c | \sigma_0, \delta_0) = \frac{1}{\sqrt{2\pi}} \frac{\delta_c - \delta_0}{\{\sigma^2 - \sigma_0^2\}^{3/2}} \exp\left\{-\frac{(\delta_c - \delta_0)^2}{2(\sigma^2 - \sigma_0^2)}\right\}. \quad \text{Eq(551) PT review}$$

Here δ_0 is the linear extrapolation of the initial overdensity that in reality grew to become δ ; σ_0 it's variance.

$\sigma \equiv \sigma(m)$ on halo-mass scale as before. Physically its easy to interpret using peak-background theory



Region will have small large scale over-density \rightarrow

the distance to the barrier for collapse is now less $\delta_c - \delta_0$. Region over large-scale overdensities collapse sooner \Rightarrow more halos

In our case we assume $\sigma_0 \ll \sigma(m)$ $\left\{ \begin{array}{l} \sigma_0 \text{ variance over} \\ \text{size } R = \frac{R_0}{1+\delta} \end{array} \right\}$

We can write

$$n(m) dm = \frac{\bar{\rho}}{m} f(\delta_c, \sigma) \left| \frac{\partial \sigma^2}{\partial m} \right| dm$$

while now

$$n(m|\delta) dm = \frac{\bar{\rho}(1+\delta)}{m} f(\delta_c, \sigma | \delta_0) \left| \frac{\partial \sigma^2}{\partial m} \right| dm$$

the volume is smaller; m at least a factor $(1+\delta)$ w.r.t the other case

Recall in this

$$\text{case } \frac{M}{V} = \bar{\rho}(1+\delta)$$

$$n(m|\delta) = \frac{\bar{\rho}}{m} (1+\delta) f(\delta_c, \sigma | \delta_0) \left| \frac{\partial \sigma^2}{\partial m} \right| dm$$

one should expand $\delta_0 = \delta_0(\delta)$ using spherical collapse. To first order $\delta_0 = \delta$

Note: in PT review $(1+\delta)$ enters through the volume over $n(m)$ is averaged \Rightarrow same answer

$$\frac{n(m|\delta)}{n(m)} = (1+\delta) \frac{f(\delta=0) + \frac{\partial f}{\partial \delta_0} \delta}{f(\delta=0)}$$

$$1 + \delta_h = (1+\delta) \left(1 - \frac{\partial \ln f}{\partial \delta_c} \delta \right)$$

$\delta_c - \delta_0$ so there is a change of sign

$f = \frac{\delta}{\sigma^3} e^{-\delta^2/2\sigma^2}$ Taking the derivative of the mass function. (43)

$$\frac{\partial f}{\partial \delta c} = \frac{1}{\sigma^3} e^{-\delta^2/2\sigma^2} - \frac{\delta}{\sigma^3} e^{-\delta^2/2\sigma^2} \frac{2\delta}{2\sigma^2}$$

$$= \left(1 - \frac{\delta^2}{\sigma^2}\right) \frac{1}{\sigma^3} e^{-\delta^2/2\sigma^2} = (1 - v^2) \frac{1}{\delta c} f$$

$$1 + \delta_h = (1 + \delta) \left(1 - \left\{\frac{1 - v^2}{\delta c}\right\} \delta\right)$$

$$\cancel{1 + \delta_h} = \cancel{1} - \left(\frac{1 - v^2}{\delta c}\right) \delta + \delta - \mathcal{O}(\delta^2)$$

$$\delta_h = \underbrace{\left\{1 + \left(\frac{v^2 - 1}{\delta c}\right)\right\}}_{b_h(m)} \delta$$

On large scales

$$\delta_h(m) = b(m) \delta$$

$$b(m) = 1 + \frac{v^2 - 1}{\delta c}$$

$$v = \frac{\delta c}{\sigma(m)}$$

↑
linearly extrapolated
to

$$v(z) = \frac{\delta c}{D(z) \sigma(m|z=0)}$$

Expanding $\delta = \delta(\delta_0)$ to 2nd, 3rd order etc one gets

$b_1(m)$ [DONE] $b_2(m)$ $b_3(m)$ etc.

If we use the ellipsoidal collapse multiplicity function

$$f_{ST}(v) = A_p \{ 1 + (qv^2)^{-p} \} \sqrt{\frac{q}{2\pi}} v e^{-qv^2/2} \quad \text{Sheth and Tormen 1999}$$

~~parameters~~

~~parameters~~

$p=0$ $A_p = \frac{1}{2}$ $q=1$ gives us back PS result.

$$b_n^{ST}(m) = 1 + \frac{qv^2-1}{\delta c} + \frac{2p/\delta c}{1 + (qv)^p}$$

see for instance
Manera Scocimano
and Sheth (2009).

Eq(22.)

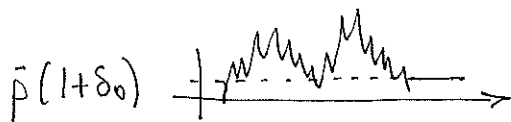
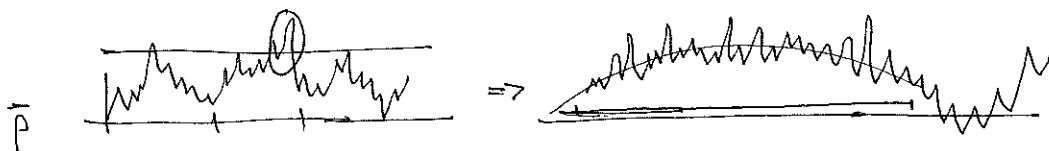
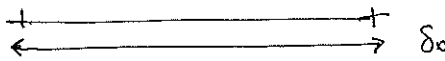
Physical Collapse

$$n(m) dm = \sqrt{\frac{2}{2\pi}} \bar{\rho} e^{-\frac{v^2}{\sigma^2}} \frac{2\sigma}{\sigma^2} dv$$

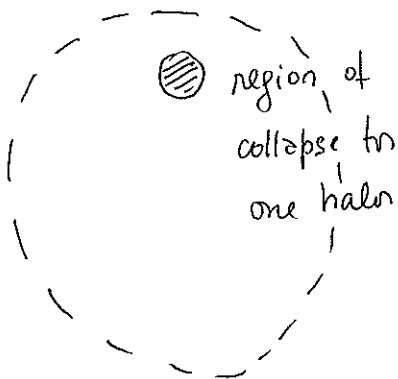
Conditional Mass Function

$$f(\sigma, \delta_c | \sigma_0, \delta_0) = \frac{1}{\sqrt{2\pi}} \frac{\delta_c - \delta_0}{(\sigma^2 - \sigma_0^2)^{3/2}} \exp \left\{ -\frac{(\delta_c - \delta_0)^2}{2(\sigma^2 - \sigma_0^2)} \right\}$$

$\delta_0 =$ linearly evolves



{ # of halos
on some
larger size }



=> we find the condition for collapse

here we assumed $\rho = \bar{\rho}$ before

Now we do the same but assuming here $\tilde{\rho} = \bar{\rho} (1 + \delta_{lin,0})$

$\delta_h =$ as function of $\bar{\rho} (1 + \delta_0)$
↑ long wavelength.

(p)

$$n(m) dm \frac{m}{M'} = \frac{\partial F}{\partial m} \Big|_{\text{conditional}} dm$$

we can now think that M' is a bit more than M or that volume is smaller but

$$p| = \bar{p}(1 + \delta_0)$$

cond.

$$dm \ n(m | \delta_0) = \frac{\partial F}{\partial \sigma} \Big|_{\frac{\partial \sigma}{\partial m}} dm$$

Conditional mass fraction:

if we think of moving the barrier $\delta_c - \delta_0$ then

$$\delta = \delta_c + \delta_s$$

$$\delta^2 = \langle \delta_c^2 \rangle + \langle \delta_s^2 \rangle + \langle \delta_c \delta_s \rangle$$

$\delta_s \delta_c \checkmark$ δ_c does not change on scales δ_s

$$\sigma_s^2 = \sigma^2 - \sigma_0^2$$

$$P(\delta > \delta_c) = \int_{\delta_c - \delta_0}^{\infty} \frac{1}{\sqrt{2\pi} \sigma_s} e^{-\frac{\delta^2}{2\sigma_s^2}}$$

↑
all the same as before
but $\delta_c \rightarrow \delta_c - \delta_0$
 $\sigma \rightarrow \sigma - \sigma_0^2$

Halo Model

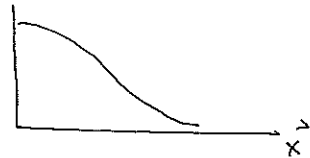
Assumptions

1- All dark matter is collapsed into halos of different masses

all we need to describe DM is:
mass function
halo bias
halo profile

$$\rho(\vec{x}) = \sum_i m_i u_{m_i}(\vec{x} - \vec{x}_i)$$

↓
halo profile



$$\int u_{m_i}(\vec{x} - \vec{x}_i) d\vec{x} = 1$$

2. Assume all halos have the same profile (!) Good to some extent see NFW profile.

$$\bar{\rho} = \langle \sum m_i u_{m_i}(\vec{x} - \vec{x}_i) \rangle = \langle \rho(\vec{x}) \rangle$$

$$\langle \sum m_i \rangle \rightarrow \int dm \ n(m) \ m$$

↑
mass function.

$\bar{\rho}^{-2} \xi$ = pairs of mass elements

$$\bar{\rho}^{-2} \xi(|\vec{x} - \vec{x}'|) = \langle \sum m_i u_{m_i}(\vec{x} - \vec{x}_i) \sum m_j u_{m_j}(\vec{x}' - \vec{x}_j) \rangle$$

$i=j \rightarrow$ one-halo term
 $i \neq j \rightarrow$ two-halo regime

$$\begin{aligned} \bar{\rho}^{-2} \xi(|\vec{x} - \vec{x}'|) &= \int \int m^2 n(m) dm \ u(x-y) u(x'-y) dy + \\ &\quad \downarrow \\ &\quad u(y) u(y+r) \\ &+ \int m_1 n(m_1) dm_1 \int m_2 n(m_2) dm_2 \int dx_1 dx_2 \xi(|x_1 - x_2|) u_{m_1} u_{m_2} \end{aligned}$$

$$\rho = \bar{\rho} (1 + \delta)$$

$$\langle \rho \rho \rangle = \bar{\rho}^2 (1 + \xi)$$

↓

disconnected
↓
piece

$$\langle \sum_i m_i u_i \sum_j m_j u_j \rangle = \langle \sum_i m_i u_i \rangle \langle \sum_j m_j u_j \rangle + \langle \sum_i m_i^2 \rangle + \langle \sum_{i \neq j} m_i m_j u_i u_j \rangle$$

$$\bar{\rho}^2 (1 + \xi) = \bar{\rho}^2 + \underbrace{\xi_{1h}}_{\text{one halo}} + \underbrace{\xi_{2h}}_{\text{two-halo}}$$

$$\xi = \xi_{1h} + \xi_{2h}$$

one halo

$$\xi_{1h} = \frac{1}{\bar{\rho}^2} \int dm m^2 n(m) \int d^3x u_m(\vec{x}) u_m(\vec{x} + \vec{r})$$

two halo
(LSS)

$$\xi_{2h} = \frac{1}{\bar{\rho}^2} \int dm_1 n(m_1) m_1 \int dm_2 n(m_2) m_2 \int d^3x_1 \int d^3x_2$$

$$u_{m_1}(x_1) u_{m_2}(x_2) \xi_{hh}(\vec{x}_1 - \vec{x}_2 + \vec{r} | m_1, m_2)$$

$$\xi_{hh}(r | m_1, m_2) = b_1(m_1) b_2(m_2) \xi(r). \quad \text{+ in the limit of large separations}$$

$$\xi_{2h} \rightarrow \xi_{lin} \quad \text{because} \quad \int dm b(m) n(m) \left(\frac{m}{\bar{\rho}}\right) = 1.$$

Halo Model for Galaxies

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Assume galaxies live inside DM halo w/ some profile

HOD \rightarrow halo occupation distribution $P(N_{gal}|M)$ prob. of finding N_{gal} in a halo of mass M .

$$\xi_{gg}^{2h}(r) = \bar{n}_g^{-2} \int dm \int dm' n(m) n(m') \langle N_{gal}(m) \rangle \langle N_{gal}(m') \rangle$$

$$\int dx_1 \int dx_2 u_1(x_1|m_1) u(x_2|m_2) \xi(\vec{x}_1 - \vec{x}_2 - r | m_1, m_2)$$

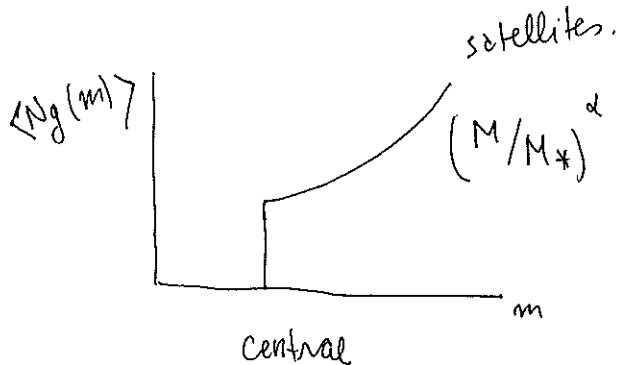
\uparrow galaxy profile

\downarrow
 $b(m_1) b(m_2) \xi(r)$

you end up w/

$$b_{gal} = \frac{1}{\bar{n}_{gal}} \int dm n(m) b(m) \langle N_{gal}(m) \rangle$$

Galaxy Bias.



Redshift Space Distortions

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In galaxy redshift surveys we don't observe directly the distance to galaxies but rather we infer that from measuring the redshift. Redshifts are due to recession speeds away from us. At low redshift one can schematically think of

$$\frac{v}{c} \sim z \rightarrow \text{from Hubble flow } H_0 r = v \sim z \rightarrow r = \frac{z}{H_0}$$

you get "r". In practice redshifts are due not only to Hubble flow but also to peculiar galaxy velocities and the latter is unfortunately correlated w/ density which is what we want to get us.

$$\vec{\chi} = \frac{\vec{r}}{a} = \frac{\vec{v}}{aH} = \frac{\vec{v}}{H}$$

$$\text{if now } \vec{v} \rightarrow \vec{v} + \vec{v}_{\text{pec}}$$

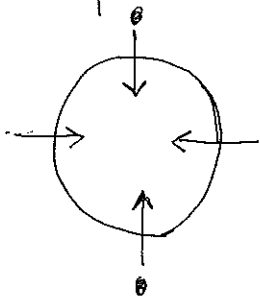
↑ ↑
due to peculiar
hubble motion
flow

$$\vec{s} = \vec{\chi} + \frac{\vec{v}_p \cdot \hat{r}}{H}$$

we only care along ~~the~~ line of sight (i.e. away from us).

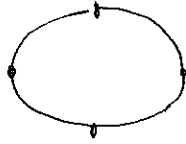
If some moves on top of Hubble flow \rightarrow we will think is farther away (has more speed than just hubble) and otherwise

Pictorially



Kaiser effect.

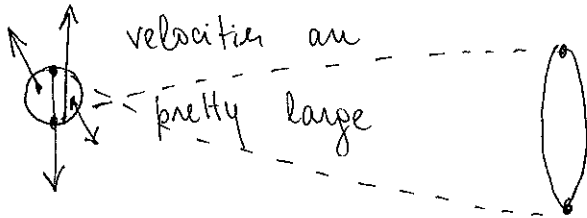
\Rightarrow



\Leftarrow motion is $\sim \text{Mpc}/h$
 velocities are few
 hundred km/s.

on large scales you
 generate an angle
 dependent distortion \Rightarrow a quadrupole

On small scales however



velocities are
 pretty large

This is called
 Finger's of God.

virial velocities are $\sim 10^3 \text{ km/s}$

typical size
 of the mapping

$$\frac{10^3 \text{ km/s}}{H_0 = 100 \text{ km/s } h/\text{Mpc}}$$

$\sim 10 \text{ Mpc}/h$ while a
 halo size is \sim few
 $h\text{pc}/h$!!

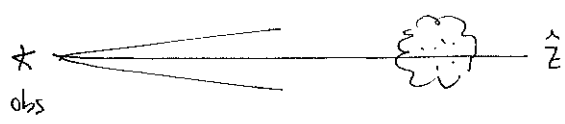
Recall that the relevant units for velocity were $-a/\dot{a} = \delta$ at large (48)

scales

$$-\frac{\vec{v}_p}{\dot{a}} \equiv \vec{u} \rightarrow \vec{v}\vec{u} = \delta$$

so \vec{z} -space mapping is now $\vec{s} = \vec{x} - f u_z \hat{z}$

↑
true comoving
coordinate.



distant observer approx \Rightarrow assume l.o.s is always at \hat{z} .

Conservation of number

The mapping cannot change the number of galaxies in a particular region (1)

$$n_s(x_s) d^3s = n(x) d^3x$$

$$\{1 + \delta_s(\vec{s})\} d^3s = \{1 + \delta(\vec{x})\} d^3x$$

Let's integrate this

$$\int e^{-i\vec{k}\cdot\vec{s}} \{1 + \delta_s(\vec{s})\} \frac{d^3s}{(2\pi)^3} = \int e^{-i\vec{k}\cdot(\vec{x} - f u_z \hat{z})} (1 + \delta(x)) \frac{d^3x}{(2\pi)^3}$$

$$\delta_D(\vec{k}) + \delta_s(\vec{k}) = \int \frac{d^3x}{(2\pi)^3} e^{-i\vec{k}\cdot\vec{x}} \{1 + \delta(x)\} e^{+i f k_z u_z}$$

Fourier mode
in \vec{z} -space

$$\delta_D(\vec{k}) + \delta_s(\vec{k}) = \int \frac{d^3x}{(2\pi)^3} e^{-i\vec{k}\cdot\vec{x}} \{1 + \delta(x)\} e^{+i f k_z u_z(\vec{x})}$$

There is a rather non-linear mapping between real and redshift space!

Now we can expand assuming $\int k_z u_z < 1$

$$\delta_D(\vec{k}) + \delta_S(\vec{k}) = \int \frac{d^3x}{(2\pi)^3} e^{-i\vec{k}\cdot\vec{x}} \{1 + \delta(\vec{x})\} \{1 + i \int k_z u_z + \dots\}$$

$$\text{Eq (**)} = \delta_D(\vec{k}) + \delta(\vec{k}) + \int \frac{d^3x}{(2\pi)^3} e^{-i\vec{k}\cdot\vec{x}} i \int k_z u_z(x)$$

↓

Recall that on large scales

$$i \int k_z \hat{u}_z(k)$$

$$\vec{\nabla} \cdot \vec{u} = \delta$$

↓

$$\text{from } u(x) = \int d^3k e^{i\vec{k}\cdot\vec{x}} \hat{u}(k)$$

Fourier transform

of \vec{u} field

$$i \vec{k} \cdot \vec{u} = \delta$$

$$\vec{u} = -i \frac{\vec{k}}{k^2} \delta$$

$$\underbrace{u_z}$$

$$\text{Back to Eq (**)} \quad \delta_S(\vec{k}) = \delta(\vec{k}) + i \int k_z \left(-i \frac{k_z}{k^2}\right) \delta$$

$$\delta_S(\vec{k}) = \delta(\vec{k}) \left\{ 1 + \int \frac{k_z^2}{k^2} \right\}$$

or defining μ angle w/ l.o.s $\Rightarrow k_z = \mu k$
cosine

$$\delta_S(\vec{k}) = (1 + \int \mu^2) \delta(\vec{k})$$

For a biased tracer with unbiased velocity field you get

$$\delta_s(k) = (b + f\mu^2) \delta(k)$$

Since $f\mu^2 > 1 \Rightarrow$ the apparent overdensity in z -space is larger than in real space \Rightarrow makes sense.

Power spectrum

$$\underbrace{\langle \delta_s(\vec{k}) \delta_s(\vec{k}') \rangle}_{P_s(\vec{k}) \delta_D(\vec{k}+\vec{k}')} = (1 + f\mu^2) (1 + f\mu'^2) \underbrace{\langle \delta(\vec{k}) \delta(\vec{k}') \rangle}_{P(\vec{k}) \delta_D(\vec{k}+\vec{k}')}$$

this implies $\mu = \mu'$
 $(\mu'^2 = \mu^2)$.

$$P_s(\vec{k}) = (b + f\mu^2)^2 P(\vec{k})$$

this is not isotropic anymore!

this one depends only on k

Typically one use multipole decomposition

$$P_s(k, \mu) = \sum_l \mathcal{L}_l(\mu) \cdot P_s^{(l)}(k)$$

↑ split of k, μ ↑

$$P_s^{(l)}(k) = \frac{(2l+1)}{2} \int_{-1}^1 P_s(k, \mu) \mathcal{L}_l(\mu) d\mu$$

For kaiser model only $l=0, 2, 4$ survive

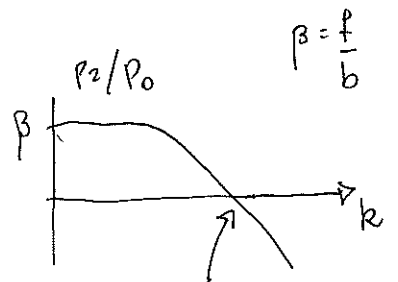
$$P_s^{(0)}(k) = \left(b^2 + \frac{2}{3} f b + \frac{f^2}{5} \right) P(k)$$

$$P_s^{(2)}(k) = \left(\frac{4}{3} b f + \frac{4}{7} f^2 \right) P(k)$$

$$P_s^{(4)}(k) = \frac{8}{35} f^2 P(k) \quad \leftarrow \text{does NOT depend on bias! but S/N is very low.}$$

Another option is quadrupole to monopole ratio to measure f/b

$\frac{P^{(2)}}{P^{(0)}}$ \rightarrow on large scales $P(k)$ cancels out and you get f/b and $f = \Omega_m^{0.6}$ measures Ω_m ! you need to get rid of bias.



quadrupole changes sign when

$\bigcirc \rightarrow \bigcirc$
Kaiser \rightarrow Fingers of God!

The effect of virial velocities is highly non-trivial

Phenomenologically one uses a damping

factor

$$P^{gal}(k) = P_* (b + f \mu^2)^2 \frac{1}{1 + k^2 \mu^2 \sigma^2 / 2}$$

$$\approx e^{-k^2 \mu^2 \sigma^2 / 2}$$

σ is a free fitting parameter.