

$$i\hbar |\dot{Q}(t)\rangle = \hat{H}_{\text{int}} |Q(t)\rangle$$

$$i\hbar (\dot{c}_g(t)|g\rangle + \dot{c}_e(t)|e\rangle) = \hbar \frac{\Omega}{2} (e^{i\Delta t - i\varphi} c_g(t)|e\rangle + e^{-i\Delta t + i\varphi} c_e(t)|g\rangle)$$

$$\begin{cases} i\dot{c}_g(t) = \frac{\Omega}{2} e^{-i\Delta t + i\varphi} c_e(t) \\ i\dot{c}_e(t) = \frac{\Omega}{2} e^{i\Delta t - i\varphi} c_g(t) \end{cases}$$

$$\dot{c}_g(t) = -i\frac{\Omega}{2} e^{-i\Delta t + i\varphi} c_e(t) \quad (1)$$

$$\dot{c}_e(t) = -i\frac{\Omega}{2} e^{i\Delta t - i\varphi} c_g(t) \quad (2)$$

Derivando (2)

$$\ddot{c}_e(t) = \frac{\Omega}{2} \Delta e^{i\Delta t - i\varphi} c_g(t) - i\frac{\Omega}{2} e^{i\Delta t - i\varphi} \dot{c}_g(t)$$

$$c_g(t) = i\frac{\Omega}{2} e^{-i\Delta t + i\varphi} \dot{c}_e(t) \quad (2) \quad \hookrightarrow \quad \dot{c}_g(t) = i\frac{\Omega}{2} e^{-i\Delta t + i\varphi} c_e(t) \quad (2)$$

$$\ddot{c}_e(t) = i\Delta \dot{c}_e(t) - \left(i\frac{\Omega}{2}\right)^2 c_e(t)$$

$$\ddot{c}_e(t) - i\Delta \dot{c}_e(t) + \left(i\frac{\Omega}{2}\right)^2 c_e(t) = 0 \quad (3)$$

esta ecuación diferencial tiene coeficientes constantes!

$$\Rightarrow c_e(t) = A_1 e^{i\alpha_1 t} + A_2 e^{i\alpha_2 t}$$

con  $\alpha_{1,2}$  las raíces de  $\alpha^2 + \Delta\alpha - \frac{\Omega^2}{4} = 0$

$$\alpha_{1,2} = \frac{\Delta}{2} \pm \frac{1}{2} \sqrt{\Delta^2 + \Omega^2}$$

$$c_e(t) = e^{i\frac{\Delta}{2}t} (A_1 e^{i\sqrt{\Delta^2 + \Omega^2}t} + A_2 e^{-i\sqrt{\Delta^2 + \Omega^2}t})$$

Por su parte,  $c_g(t)$  puede encontrarse resolviendo a (1)

$$\begin{aligned} \dot{c}_g(t) &= -i\frac{\Omega}{2} e^{-i\Delta t + i\varphi} e^{i\frac{\Delta}{2}t} (A_1 e^{i\sqrt{\Delta^2 + \Omega^2}t} + A_2 e^{-i\sqrt{\Delta^2 + \Omega^2}t}) \\ &= -i\frac{\Omega}{2} e^{i\varphi} e^{-i\frac{\Delta}{2}t} (A_1 e^{i\sqrt{\Delta^2 + \Omega^2}t} + A_2 e^{-i\sqrt{\Delta^2 + \Omega^2}t}) \end{aligned}$$

$$\Rightarrow c_g(t) = e^{i\varphi} e^{-i\frac{\Delta}{2}t} \frac{\Omega}{2} \left\{ \frac{A_1 e^{i\sqrt{\Delta^2 + \Omega^2}t}}{\frac{\Delta}{2} - \sqrt{\Delta^2 + \Omega^2}} + \frac{A_2 e^{-i\sqrt{\Delta^2 + \Omega^2}t}}{\frac{\Delta}{2} + \sqrt{\Delta^2 + \Omega^2}} \right\}$$

Las constantes  $A_{1,2}$  se fijan recurriendo a la condición inicial

$$c_e(0) = 1$$

$$c_g(0) = 0$$

$$c_e(0) = A_1 + A_2 = 1 \quad (4)$$

$$c_g(0) = \frac{\Omega}{2} \left\{ \frac{A_1}{\frac{\Delta}{2} - \sqrt{\Delta^2 + \Omega^2}} + \frac{A_2}{\frac{\Delta}{2} + \sqrt{\Delta^2 + \Omega^2}} \right\} = 0 \quad (5)$$

$$(5) \Rightarrow \frac{A_2}{\frac{\Delta}{2} + \sqrt{\Delta^2 + \Omega^2}} = - \frac{A_1}{\frac{\Delta}{2} - \sqrt{\Delta^2 + \Omega^2}}$$

$$A_2 = - \frac{\Delta + 2\sqrt{\Delta^2 + \Omega^2}}{\Delta - 2\sqrt{\Delta^2 + \Omega^2}} A_1$$

$$(4) \quad A_1 - \frac{\Delta + 2\sqrt{\Delta^2 + \Omega^2}}{\Delta - 2\sqrt{\Delta^2 + \Omega^2}} A_1 = 1$$

$$A_1 \frac{-4\sqrt{\Delta^2 + \Omega^2}}{\Delta - 2\sqrt{\Delta^2 + \Omega^2}} = 1 \Rightarrow A_1 = - \frac{\frac{\Delta}{2} - \sqrt{\Delta^2 + \Omega^2}}{\sqrt{\Delta^2 + \Omega^2}}$$

$$A_2 = \frac{\frac{\Delta}{2} + \sqrt{\Delta^2 + \Omega^2}}{\sqrt{\Delta^2 + \Omega^2}}$$

$$c_e(t) = e^{\frac{i\Delta t}{2}} (A_1 e^{i\sqrt{\Delta^2 + \Omega^2} t} + A_2 e^{-i\sqrt{\Delta^2 + \Omega^2} t})$$

$$= \frac{e^{\frac{i\Delta t}{2}}}{\sqrt{\Delta^2 + \Omega^2}} \left( - \left( \frac{\Delta}{2} - \sqrt{\Delta^2 + \Omega^2} \right) e^{i\sqrt{\Delta^2 + \Omega^2} t} + \left( \frac{\Delta}{2} + \sqrt{\Delta^2 + \Omega^2} \right) e^{-i\sqrt{\Delta^2 + \Omega^2} t} \right)$$

$$c_e(t) = e^{\frac{i\Delta t}{2}} \left\{ \cos(\sqrt{\Delta^2 + \Omega^2} t) - i \frac{\Delta}{\sqrt{\Delta^2 + \Omega^2}} \sin(\sqrt{\Delta^2 + \Omega^2} t) \right\}$$

$$c_g(t) = e^{i\varphi} e^{-\frac{i\Delta t}{2}} \frac{\Omega}{2} \left\{ \frac{A_1 e^{i\sqrt{\Delta^2 + \Omega^2} t}}{\frac{\Delta}{2} - \sqrt{\Delta^2 + \Omega^2}} + \frac{A_2 e^{-i\sqrt{\Delta^2 + \Omega^2} t}}{\frac{\Delta}{2} + \sqrt{\Delta^2 + \Omega^2}} \right\}$$

$$c_g(t) = -e^{i\varphi} e^{-\frac{i\Delta t}{2}} \frac{\Omega}{\sqrt{\Delta^2 + \Omega^2}} \sin(\sqrt{\Delta^2 + \Omega^2} t)$$