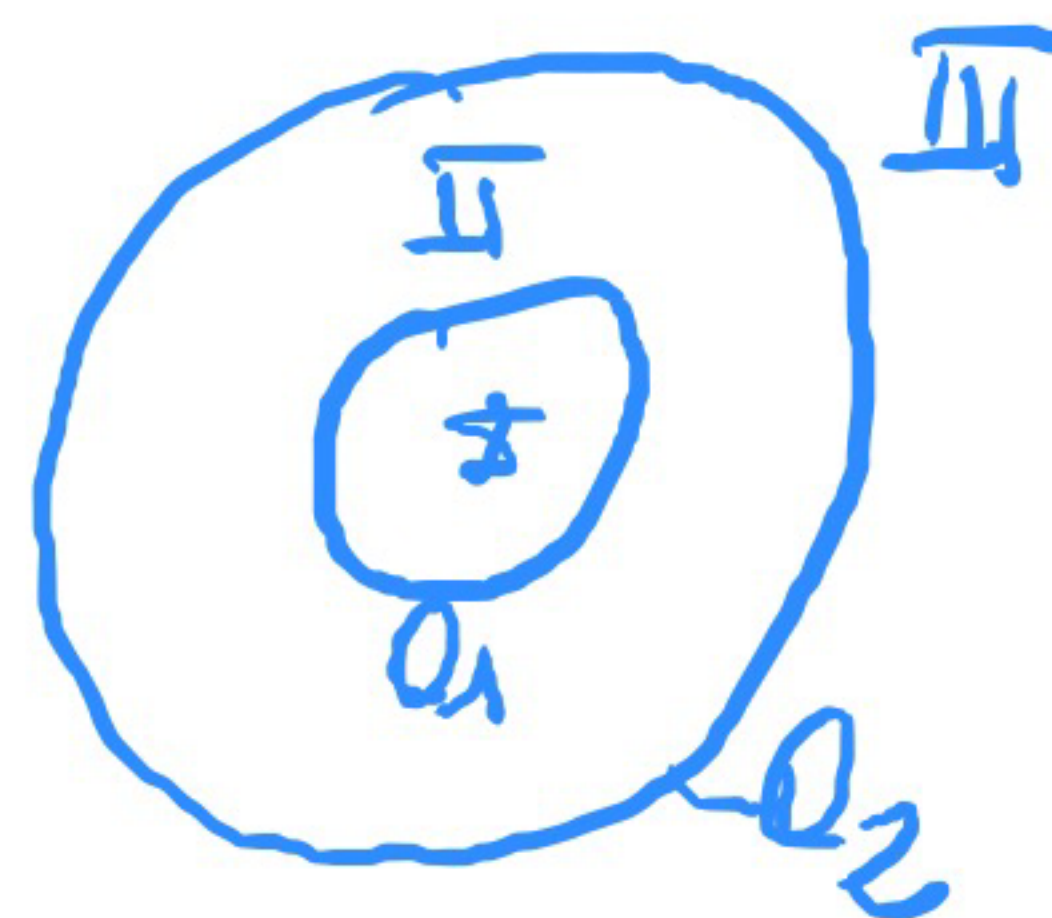


Ⓐ

$$V(r) = \begin{cases} \frac{Q}{4\pi\epsilon_0 R} \\ \frac{Q}{4\pi\epsilon_0 r} \end{cases}$$

$$r < R$$

$$r > R$$



$$V(r) = 0$$

$$r \rightarrow \infty$$

$$V(r=a) = 0$$

$$V(r=2a) = V_0$$

I

$$\frac{Q_1}{4\pi\epsilon_0 a} + \frac{Q_2}{4\pi\epsilon_0 a^2}$$

$$r < a$$

II

$$\frac{Q_1}{4\pi\epsilon_0 r} + \frac{Q_2}{8\pi\epsilon_0 a}$$

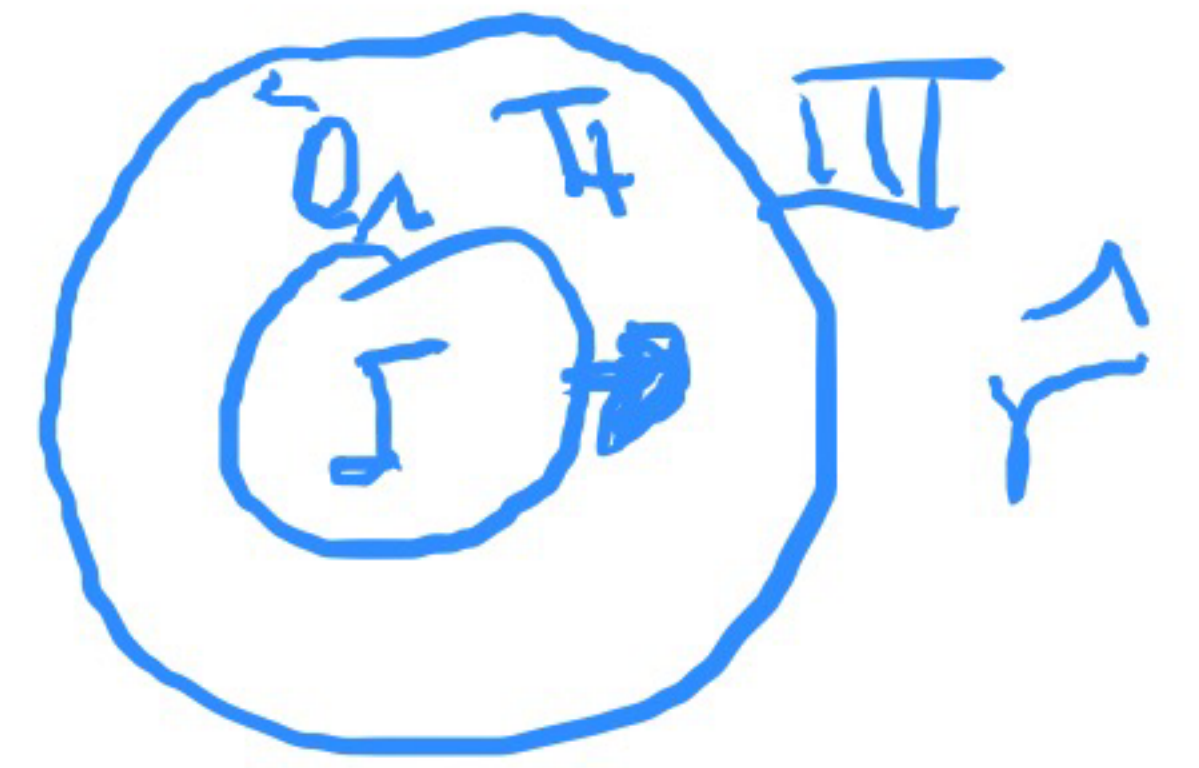
$$a < r < 2a$$

III

$$\frac{Q_1}{4\pi\epsilon_0 r} + \frac{Q_2}{4\pi\epsilon_0 r}$$

$$r > 2a$$

$$\begin{array}{l}
 \text{I} \quad 0 \quad r < a \\
 \text{II} \quad \frac{A_1}{r} + B_1 \quad a < r < 2a \\
 \text{III} \quad \frac{A_2}{r} + B_2 \quad r > 2a
 \end{array}
 \left. \vphantom{\begin{array}{l} \text{I} \\ \text{II} \\ \text{III} \end{array}} \right\} = V(r)$$



Continuidad en $r=2a$ ~~$r=a$~~

$$V(r=a) = 0 \quad V(r=2a) = V_0$$

ELISO $V(r) = 0 \quad \implies \quad B_2 = 0$
 $r \rightarrow \infty$

$$\begin{array}{l}
 \implies A_1, A_2, B_1 \implies \left. \begin{array}{l} \vec{E}_1 \\ \vec{E}_2 - \vec{E}_1 \cdot \hat{n} \end{array} \right|_{r=a} = \frac{\sigma_1}{\epsilon_0} \\
 \hat{n} \text{ normal } \pm a \pm
 \end{array}$$

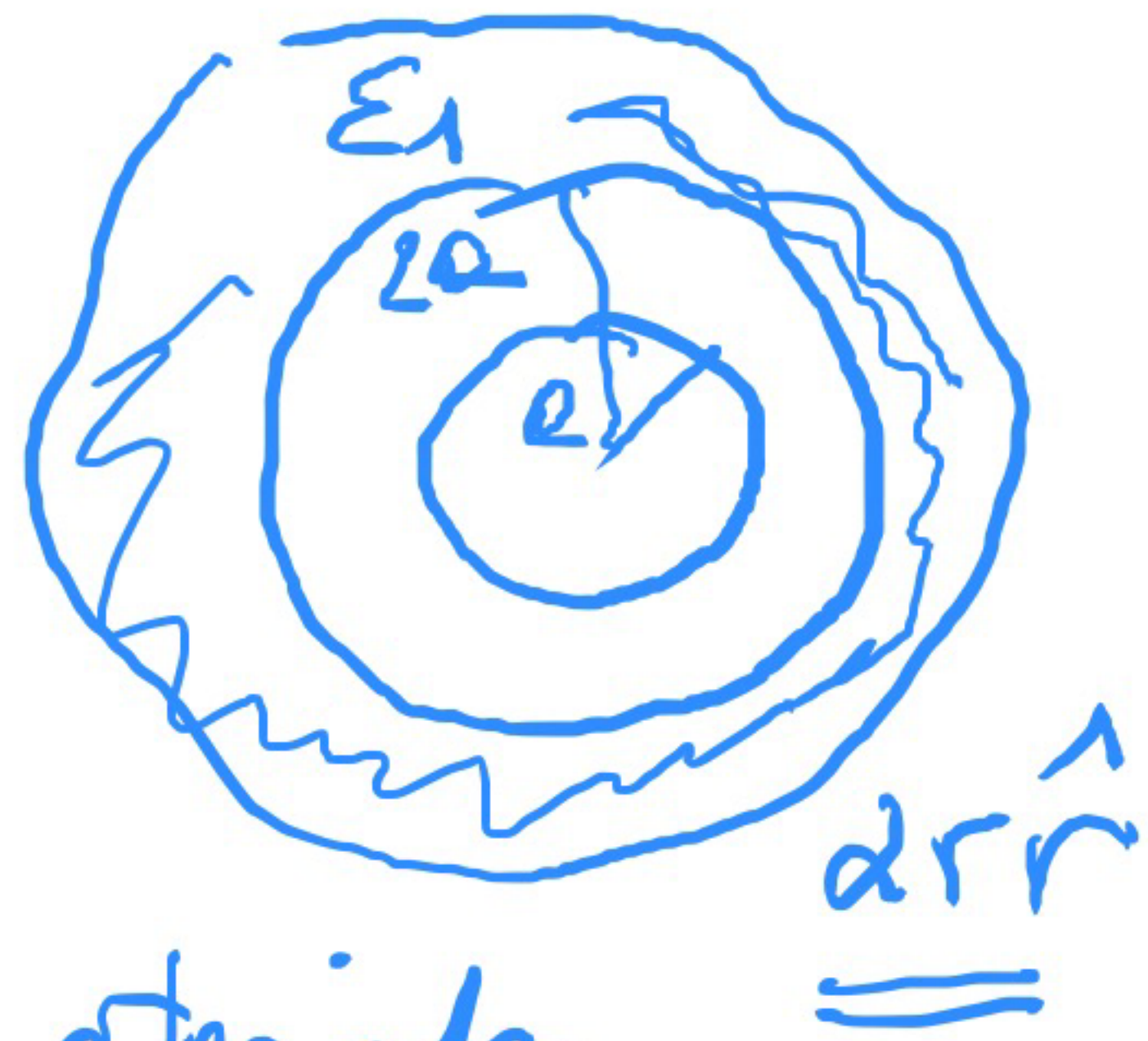
$$\begin{array}{l}
 Q_1 = -8\pi\epsilon_0 a V_0 \\
 Q_2 = 16\pi\epsilon_0 V_0 a
 \end{array}$$

$$\vec{\nabla} \times \vec{D} = \vec{\nabla} \times \vec{P}$$

$$\vec{\nabla} \times \vec{E} = 0$$

$$\vec{\nabla} \cdot \vec{D} = \rho_L$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho_L}{\epsilon_0} = \frac{\rho_L + \rho_P}{\epsilon_0}$$



$$0 < r < 2a$$

$$\vec{P} = 0 \Rightarrow \vec{\nabla} \times \vec{P} = 0$$

x que no hay medios materiales

$$2a < r < 3a$$

medio L. I. H

$$\vec{P} = \epsilon_0 \chi \vec{E} \Rightarrow \vec{\nabla} \times \vec{P} = \epsilon_0 \chi \vec{\nabla} \times \vec{E} = 0$$

$$r > 3a$$

$$\vec{P} = \alpha r \hat{r}$$

$$\vec{\nabla} \times \vec{P}$$

$$= \frac{1}{r \sin \theta} \left[\frac{\partial (P_\theta \sin \theta)}{\partial \theta} - \frac{\partial P_\theta}{\partial \varphi} \right] \hat{r} +$$

$$\frac{1}{r} \left(\frac{\partial P_r}{\partial \varphi} \frac{1}{\sin \theta} - \frac{\partial (P_\varphi r)}{\partial r} \right) \hat{\theta} + \frac{1}{r} \left[\frac{\partial (P_\theta r)}{\partial r} - \frac{\partial P_r}{\partial \theta} \right] \hat{\varphi} = 0$$

$$\iiint \vec{D} \cdot d\vec{S} = Q_{enc}$$

$$\iint \vec{E} \cdot d\vec{S} = \frac{Q_T}{\epsilon_0}$$

$$\vec{D} = D(r) \hat{r}$$

$$\int_0^{2\pi} \int_0^{\pi} D(r) \hat{r} \cdot \hat{r} r^2 \sin\theta d\theta d\phi = 4\pi r^2 D(r) = Q_{enc}$$

$$Q_{enc} = \begin{cases} Q_1 & r < a \\ Q_2 + Q_1 & a < r < 2a \\ & r > 2a \end{cases}$$

$$\rightarrow \vec{D} = \epsilon_0 \vec{E} + \vec{P} \rightarrow \text{siempre}$$

$$\swarrow \vec{D} = \epsilon \vec{E} \rightarrow \text{L.I.H. medio}$$

$$\vec{D} = \epsilon_0 \vec{E}$$

$$0 < r < 2a$$

\rightarrow vacío

$$\vec{E} = \vec{D}$$

$$2a < r < 3a$$

L.I.H.

$$\vec{E} = \frac{\vec{D}}{\epsilon_0}$$

$$r > 3a$$

$$\Rightarrow \vec{E} = \frac{\vec{D} - \vec{P}}{\epsilon_0}$$

$$\epsilon_1 = \epsilon_0 (1 + \chi_1)$$

$$\vec{P} = \epsilon_0 \chi_1 \vec{E}$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} \Rightarrow \vec{P} = \vec{D} - \epsilon_0 \vec{E}$$

$$p_r = -\vec{\nabla} \cdot \vec{P}$$

$$\vec{\nabla} \cdot \vec{P} = \frac{1}{r^2} \frac{d}{dr} (r^2 P_r)$$

$$= \frac{1}{r^2} \frac{d}{dr} \left[r^2 \frac{Q_1 + Q_2}{4\pi r^2} \left(1 - \frac{\epsilon_0}{\epsilon_1}\right) \right] = 0$$

$$2a < r < 3a \Rightarrow p_r = 0$$

$$r > 3a \quad p_r = -\frac{1}{r^2} \frac{d}{dr} (r^2 A r) = -\frac{1}{r^2} A 3r^2 = -3A$$

$$p_r = -3A$$

$$\left. \begin{array}{l} 0 \quad r < 2a \\ \frac{Q_1 + Q_2}{4\pi r^2} \left(1 - \frac{\epsilon_0}{\epsilon_1}\right) r^3 \\ A r \quad r > 3a \end{array} \right\} \begin{array}{l} r < 2a \\ 2a < r < 3a \\ r > 3a \end{array}$$