

Física de muchos cuerpos

Año 2020

Guía 6 - Ejercicio 5

Demostrar que si $c_l(t) = \exp\left(-i\frac{\epsilon_l t}{\hbar}\right) c_l$, los operadores fermiónicos de creación y destrucción satisfacen:

$$(a) \overline{c_k^\dagger(t')c_j(t)} = -\overline{c_j(t)c_k^\dagger(t')}.$$

$$(b) \overline{c_k(t')c_j(t)} = 0 = \overline{c_k^\dagger(t')c_j^\dagger(t)}.$$

$$(c) \overline{\psi(x;t)\psi^\dagger(y;t')} = -\overline{\psi^\dagger(y;t')\psi(x;t)}.$$

$$(d) \overline{\psi(x;t)\psi(y;t')} = 0 = \overline{\psi^\dagger(x;t)\psi^\dagger(y;t')}.$$

Preliminares

- Orden temporal:

Si $t < t' \implies T[A(t)B(t')] = s B(t')A(t) \quad / \quad s = -1$ para fermiones.

- Orden normal:

$N[A_l(t')B_k^\dagger(t)] = s B_k^\dagger(t)A_l(t') \quad / \quad s = -1$ para fermiones.

$N[A_l(t')B_k(t)] = A_l(t')B_k(t).$

$N[A_l^\dagger(t')B_k^\dagger(t)] = A_l^\dagger(t')B_k^\dagger(t).$

- Contracción:

$\overline{A(t)B(t')} = T[A(t)B(t')] - N[A(t)B(t')].$

$\overline{\sum_i \alpha_i A_i(t) \sum_j \beta_j B_j^\dagger(t')} = \sum_{i,j} \alpha_i \beta_j \overline{A_i(t)B_j^\dagger(t')}$ (linealidad que proviene de la linealidad de T, N).

Resolución (a)

- Caso $\epsilon_k, \epsilon_j \leq \epsilon_F : c_k^\dagger = b_k \wedge c_j = b_j^\dagger$.

$$\overline{c_k^\dagger(t')c_j(t)} = \overline{b_k(t')b_j^\dagger(t)} = T [b_k(t')b_j^\dagger(t)] - N [b_k(t')b_j^\dagger(t)] =$$

$$\left\{ \begin{array}{l} t < t' : b_k(t')b_j^\dagger(t) + b_j^\dagger(t)b_k(t') = -T [b_j^\dagger(t)b_k(t')] + N [b_j^\dagger(t)b_k(t')] \\ t > t' : -b_j^\dagger(t)b_k(t') + b_j^\dagger(t)b_k(t') = -T [b_j^\dagger(t)b_k(t')] + N [b_j^\dagger(t)b_k(t')] \end{array} \right\} = -\overline{b_j^\dagger(t)b_k(t')} = -\overline{c_j(t)c_k^\dagger(t')}.$$

- Caso $\epsilon_k \leq \epsilon_F < \epsilon_j : c_k^\dagger = b_k \wedge c_j = a_j$.

$$\overline{c_k^\dagger(t')c_j(t)} = \overline{b_k(t')a_j(t)} = T [b_k(t')a_j(t)] - N [b_k(t')a_j(t)] =$$

$$\left\{ \begin{array}{l} t < t' : b_k(t')a_j(t) - b_k(t')a_j(t) = -T [a_j(t)b_k(t')] - b_k(t')a_j(t) \\ t > t' : -a_j(t)b_k(t') - b_k(t')a_j(t) = -T [a_j(t)b_k(t')] - b_k(t')a_j(t) \end{array} \right\} = -T [a_j(t)b_k(t')] - b_k(t')a_j(t).$$

Auxiliar:

$$b_k(t')a_j(t) = c_k^\dagger(t')c_j(t) = \exp\left(i\frac{\epsilon_k t'}{\hbar}\right) \exp\left(-i\frac{\epsilon_j t}{\hbar}\right) c_k^\dagger c_j = \exp\left(i\frac{\epsilon_k t'}{\hbar}\right) \exp\left(-i\frac{\epsilon_j t}{\hbar}\right) (\delta_{jk} - c_j c_k^\dagger) =$$

$$-c_j(t)c_k^\dagger(t'), \text{ pues } j \neq k \implies b_k(t')a_j(t) = -a_j(t)b_k(t').$$

$$-T [a_j(t)b_k(t')] - b_k(t')a_j(t) = -T [a_j(t)b_k(t')] + a_j(t)b_k(t') = -T [a_j(t)b_k(t')] + N [a_j(t)b_k(t')] =$$

$$-\overline{a_j(t)b_k(t')} = -\overline{c_j(t)c_k^\dagger(t')}.$$

- Caso $\epsilon_j \leq \epsilon_F < \epsilon_k : c_k^\dagger = a_k^\dagger \wedge c_j = b_j^\dagger$.

$$\overline{c_k^\dagger(t')c_j(t)} = \overline{a_k^\dagger(t')b_j^\dagger(t)} = T [a_k^\dagger(t')b_j^\dagger(t)] - N [a_k^\dagger(t')b_j^\dagger(t)] =$$

$$\left\{ \begin{array}{l} t < t' : a_k^\dagger(t')b_j^\dagger(t) - a_k^\dagger(t')b_j^\dagger(t) = -T [b_j^\dagger(t)a_k^\dagger(t')] + N [b_j^\dagger(t)a_k^\dagger(t')] \\ t > t' : -b_j^\dagger(t)a_k^\dagger(t') - a_k^\dagger(t')b_j^\dagger(t) = -T [b_j^\dagger(t)a_k^\dagger(t')] + N [b_j^\dagger(t)a_k^\dagger(t')] \end{array} \right\} = -\overline{b_j^\dagger(t)a_k^\dagger(t')} = -\overline{c_j(t)c_k^\dagger(t')}.$$

- Caso $\epsilon_F < \epsilon_k, \epsilon_j : c_k^\dagger = a_k^\dagger \wedge c_j = a_j$.

$$\overline{c_k^\dagger(t')c_j(t)} = \overline{a_k^\dagger(t')a_j(t)} = T [a_k^\dagger(t')a_j(t)] - N [a_k^\dagger(t')a_j(t)] =$$

$$\left\{ \begin{array}{l} t < t' : a_k^\dagger(t')a_j(t) - a_k^\dagger(t')a_j(t) = -T [a_j(t)a_k^\dagger(t')] + N [a_j(t)a_k^\dagger(t')] \\ t > t' : -a_j(t)a_k^\dagger(t') - a_k^\dagger(t')a_j(t) = -T [a_j(t)a_k^\dagger(t')] + N [a_j(t)a_k^\dagger(t')] \end{array} \right\} = -\overline{a_j(t)a_k^\dagger(t')} = -\overline{c_j(t)c_k^\dagger(t')}.$$

Resolución (b)

$$\text{q.v.q } \overline{c_k(t')c_j(t)} = 0.$$

- Caso $\epsilon_k, \epsilon_j \leq \epsilon_F : c_k = b_k^\dagger \wedge c_j = b_j^\dagger$.

$$\begin{aligned} \overline{c_k(t')c_j(t)} &= \overline{b_k^\dagger(t')b_j^\dagger(t)} = T \left[b_k^\dagger(t')b_j^\dagger(t) \right] - N \left[b_k^\dagger(t')b_j^\dagger(t) \right] = \\ &\left\{ \begin{array}{l} t < t' : b_k^\dagger(t')b_j^\dagger(t) - b_k^\dagger(t)b_j^\dagger(t) \\ t > t' : -b_j^\dagger(t)b_k^\dagger(t') - b_k^\dagger(t')b_j^\dagger(t) = - \left\{ b_j^\dagger(t), b_k^\dagger(t') \right\} \end{array} \right\} = 0. \end{aligned}$$

- Caso $\epsilon_k \leq \epsilon_F < \epsilon_j : c_k = b_k^\dagger \wedge c_j = a_j$.

$$\begin{aligned} \overline{c_k(t')c_j(t)} &= \overline{b_k^\dagger(t')a_j(t)} = T \left[b_k^\dagger(t')a_j(t) \right] - N \left[b_k^\dagger(t')a_j(t) \right] = \\ &\left\{ \begin{array}{l} t < t' : b_k^\dagger(t')a_j(t) - b_k^\dagger(t)a_j(t) \\ t > t' : -a_j(t)b_k^\dagger(t') - b_k^\dagger(t')a_j(t) = - \left\{ a_j(t), b_k^\dagger(t') \right\} \end{array} \right\} = 0. \end{aligned}$$

- Caso $\epsilon_j \leq \epsilon_F < \epsilon_k : c_k = a_k \wedge c_j = b_j^\dagger$.

$$\begin{aligned} \overline{c_k(t')c_j(t)} &= \overline{a_k(t')b_j^\dagger(t)} = T \left[a_k(t')b_j^\dagger(t) \right] - N \left[a_k(t')b_j^\dagger(t) \right] = \\ &\left\{ \begin{array}{l} t < t' : a_k(t')b_j^\dagger(t) + b_j^\dagger(t)a_k(t') = \left\{ a_k(t'), b_j^\dagger(t) \right\} \\ t > t' : -b_j^\dagger(t)a_k(t') + b_j^\dagger(t)a_k(t') \end{array} \right\} = 0. \end{aligned}$$

- Caso $\epsilon_F < \epsilon_k, \epsilon_j : c_k = a_k \wedge c_j = a_j$.

$$\begin{aligned} \overline{c_k(t')c_j(t)} &= \overline{a_k(t')a_j(t)} = T \left[a_k(t')a_j(t) \right] - N \left[a_k(t')a_j(t) \right] = \\ &\left\{ \begin{array}{l} t < t' : a_k(t')a_j(t) - a_k(t')a_j(t) \\ t > t' : -a_j(t)a_k(t') - a_k(t')a_j(t) = - \left\{ a_j(t), a_k(t') \right\} \end{array} \right\} = 0. \end{aligned}$$

Luego, por idéntico razonamiento, podemos ver que: $\overline{c_k^\dagger(t')c_j^\dagger(t)} = 0$.

Resolución (c)

$$\overline{\psi(x;t)\psi^\dagger(y;t')} = \overline{\sum_i \alpha_i c_i(t) \sum_j \beta_j c_j^\dagger(t')} = \sum_{i,j} \alpha_i \beta_j \overline{c_i(t) c_j^\dagger(t')} = - \sum_{i,j} \alpha_i \beta_j \overline{c_j^\dagger(t') c_i(t)} = - \overline{\psi(y;t')^\dagger \psi(x;t)}.$$

Observación:

Como $\langle \phi_0 | N[\dots] | \phi_0 \rangle = 0$, luego:

$$\overline{\psi(x;t)_H \psi^\dagger(y;t')_H} = \frac{1}{\langle \phi_0 | \phi_0 \rangle} \langle \phi_0 | T [\psi(x;t)_H \psi^\dagger(y;t')_H] | \phi_0 \rangle = iG^{(0)}(x,t;y,t').$$

Resolución (d)

$$\overline{\psi(x;t)\psi(y;t')} = \sum_{i,j} \alpha_i \beta_j \overline{c_i(t) c_j(t')} = 0.$$

$$\overline{\psi^\dagger(x;t)\psi^\dagger(y;t')} = \sum_{i,j} \alpha_i \beta_j \overline{c_i^\dagger(t) c_j^\dagger(t')} = 0.$$