

Guía 6: Oscilador Armónico.

$$H = \frac{p^2}{2m} + \frac{m\omega^2 x^2}{2} \quad \left\{ \begin{array}{l} a = \sqrt{\frac{m\omega}{2\hbar}} \left(x + \frac{i p}{m\omega} \right) \\ a^\dagger = \sqrt{\frac{m\omega}{2\hbar}} \left(x - \frac{i p}{m\omega} \right) \end{array} \right.$$

Solución Algebraica

$$\Rightarrow [a, a^\dagger] = 1$$

$$a|n\rangle = \sqrt{n}|n-1\rangle \quad a^\dagger|n\rangle = \sqrt{n+1}|n+1\rangle$$

$$H = \hbar\omega \left(\underbrace{a^\dagger a}_N + \frac{1}{2} \right) \quad \begin{array}{l} [N, a] = -a \\ [N, a^\dagger] = a^\dagger \end{array}$$

$$E_n = \hbar\omega \left(n + \frac{1}{2} \right) \quad n = 0, 1, \dots$$

$$|n\rangle = \frac{1}{\sqrt{n!}} a^{\dagger n} |0\rangle$$

PA: Valores medios, incertezas
 $\langle n|x|n\rangle = \langle n|p|n\rangle = 0$ (No más clásico)

Probar que el estado $|n\rangle$:

$$\text{Var}(x) \text{Var}(p) = \left(n + \frac{1}{2} \right)^2 \hbar^2$$

$n=0$ da la mínima incerteza

\Rightarrow es una gaussiana centrada en el origen.

Cálculo de $\psi_0(x) = \langle x|0\rangle$:

$$\langle x|a|0\rangle = 0$$

$$\langle x|\cancel{x}|0\rangle + \frac{i}{m\omega} \langle x|p|0\rangle = 0$$

$$x\psi_0(x) + \frac{-i\hbar}{m\omega} \frac{\partial}{\partial x} \psi_0(x) = 0$$

$$\neq \psi_0(x) = N e^{-\frac{x^2}{4\sigma^2}}$$

$$\sigma^2 = \frac{\hbar}{2m\omega}$$

Guia 6: Oscilador armónico

$$[a, a^\dagger] = 1$$

[P4] Estados coerentes.

$$a|\alpha\rangle = \alpha|\alpha\rangle$$

$$\alpha \in \mathbb{C}$$

a : no hermítico

$$(a) \quad \langle \alpha | a | \alpha \rangle = \alpha \Rightarrow \langle \alpha | a^\dagger | \alpha \rangle = \alpha^*$$

$$\langle \alpha | a^2 | \alpha \rangle = \alpha^2 \Rightarrow \langle \alpha | a^{\dagger 2} | \alpha \rangle = \alpha^{*2}$$

$$(b) \quad N = a^\dagger a$$

$$\langle \alpha | N | \alpha \rangle = \langle \alpha | a^\dagger a | \alpha \rangle = |\alpha|^2$$

$$a|\alpha\rangle = \alpha|\alpha\rangle$$

$$\langle \alpha | a^\dagger = \alpha^* \langle \alpha |$$

$$\text{Var}(N)_{|\alpha\rangle} = \langle \alpha | N^2 | \alpha \rangle - (\langle \alpha | N | \alpha \rangle)^2$$

$$\langle \alpha | a^\dagger a a^\dagger a | \alpha \rangle$$

$$|\alpha|^2 \langle \alpha | a^\dagger a + \underbrace{[a^\dagger, a]}_{+1} | \alpha \rangle$$

$$\text{Var}(N)_{|\alpha\rangle} = |\alpha|^2$$

$$(c) \quad H = \hbar\omega(N + \frac{1}{2}) \Rightarrow \langle \alpha | H | \alpha \rangle = \hbar\omega(|\alpha|^2 + \frac{1}{2})$$

$$\text{Var}(H)_{|\alpha\rangle} = \langle \alpha | H^2 | \alpha \rangle - (\langle \alpha | H | \alpha \rangle)^2$$

$$= \frac{\hbar^2\omega^2}{4} \langle \alpha | N^2 + N + \frac{1}{4} | \alpha \rangle - \hbar^2\omega^2 \left(|\alpha|^2 + \frac{1}{2} \right)^2$$

$$= \frac{\hbar^2\omega^2}{4} \left(|\alpha|^4 + |\alpha|^2 + |\alpha|^2 + \frac{1}{4} \right) - \hbar^2\omega^2 \left(|\alpha|^4 + |\alpha|^2 + \frac{1}{4} \right)$$

$$\text{Var}(H) = \frac{\hbar^2\omega^2}{4} |\alpha|^2$$

$$(d) \quad x = \sqrt{\frac{\hbar}{2m\omega}} (a + a^\dagger) \quad p = \sqrt{\frac{\hbar m\omega}{2}} \frac{(a - a^\dagger)}{i}$$

$$\langle x | x | \alpha \rangle = \sqrt{\frac{\hbar}{2m\omega}} (\alpha + \alpha^*) \quad \langle p | p | \alpha \rangle = \sqrt{\frac{\hbar m\omega}{2}} \frac{1}{i} (\alpha - \alpha^*)$$

$$\langle x \rangle_\alpha = 2\sqrt{\frac{\hbar}{2m\omega}} \operatorname{Re} \alpha \quad \langle p \rangle_\alpha = 2\sqrt{\frac{\hbar m\omega}{2}} \operatorname{Im}(\alpha)$$

$$\begin{aligned} \bullet \operatorname{Var}(x) &= \frac{\hbar}{2m\omega} \left[\langle \alpha | a^2 + a a^\dagger + a^\dagger a + a^{\dagger 2} | \alpha \rangle - (\alpha + \alpha^*)^2 \right] \\ &= \frac{\hbar}{2m\omega} \left[\cancel{\alpha^2} + 2|\alpha|^2 + 1 + \cancel{\alpha^{*2}} - \alpha^2 - 2|\alpha|^2 - \alpha^{*2} \right] \end{aligned}$$

$$\operatorname{Var}(x) = \frac{\hbar}{2m\omega} = \epsilon^2 \quad \text{No depende de } \alpha$$

$$\begin{aligned} (e) \operatorname{Var}(p) &= \frac{\hbar m\omega}{2} \left[\langle \alpha | a^2 - a a^\dagger - a^\dagger a + a^{\dagger 2} | \alpha \rangle - (\alpha - \alpha^*)^2 \right] \\ &= \frac{\hbar m\omega}{2} \left[\cancel{\alpha^2} - 2|\alpha|^2 - 1 - \cancel{\alpha^{*2}} - \alpha^2 + 2|\alpha|^2 - \alpha^{*2} \right] \end{aligned}$$

$$\operatorname{Var}(p) = \frac{\hbar m\omega}{2} \quad \text{No depende de } \alpha$$

$$(f) \quad \operatorname{Var}(x) \operatorname{Var}(p) = \frac{\hbar^2}{4} = \frac{\langle \alpha | [x, p] | \alpha \rangle^2}{4}$$

Mínima incertidumbre.

⇒ El estado coherente es una gaussiana con los valores medios $\langle x \rangle$ y $\langle p \rangle$:

$$\langle x | \alpha \rangle = \frac{1}{(\sqrt{\pi} \epsilon)^2} e^{i \frac{\langle p \rangle x}{\hbar}} e^{-\frac{(x - \langle x \rangle)^2}{4\epsilon^2}}$$

$$\langle x | \alpha \rangle = \langle x | e^{i \frac{\langle p \rangle x}{\hbar} - i \frac{\langle x \rangle p}{\hbar}} | 0 \rangle e^{-\frac{i \langle x \rangle \langle p \rangle}{2\hbar}}$$

Baker-Campbell-Hausdorff: $e^{A+B} = e^A e^B e^{-[A,B]/2}$

Görög: Oscillations answers

Cont [PK]

(9) Calculate $\langle \alpha | \hat{x}(t) | \alpha \rangle$ $\langle \alpha | \hat{p}(t) | \alpha \rangle$

Write a better $\hat{a}(t)$:

$$\dot{\hat{a}}(t) = \frac{[\hat{a}, H]}{i\hbar} = \frac{\hbar\omega[\hat{a}, \hat{a}^\dagger]}{i\hbar}$$

$$\dot{\hat{a}}(t) = \frac{\omega}{i} (\underbrace{[\hat{a}, \hat{a}^\dagger]}_1 \hat{a} + \hat{a}^\dagger [\hat{a}, \hat{a}])$$

$$\dot{\hat{a}}(t) = -i\omega \Rightarrow \hat{a}(t) = \hat{a}(0) e^{-i\omega t}$$

$$\hat{a}^\dagger(t) = \hat{a}^\dagger(0) e^{i\omega t}$$

$$\hat{x}(t) = \sqrt{\frac{\hbar}{2m\omega}} \left[\sqrt{\frac{m\omega}{2\hbar}} \left(\hat{x}(0) + i \frac{\hat{p}(0)}{m\omega} \right) e^{-i\omega t} + \sqrt{\frac{m\omega}{2\hbar}} \left(\hat{x}(0) - i \frac{\hat{p}(0)}{m\omega} \right) e^{i\omega t} \right]$$

$$\hat{x}(t) = \hat{x}(0) \cos \omega t + \frac{\hat{p}(0)}{m\omega} \sin \omega t.$$

$$\hat{p}(t) = \sqrt{\frac{\hbar m \omega}{2i}} \left[\sqrt{\frac{i m \omega}{2\hbar}} \frac{1}{i} \left(\hat{x}(0) + i \frac{\hat{p}(0)}{m\omega} \right) e^{-i\omega t} - \sqrt{\frac{m \omega}{2\hbar}} \frac{1}{i} \left(\hat{x}(0) - i \frac{\hat{p}(0)}{m\omega} \right) e^{i\omega t} \right]$$

$$\hat{p}(t) = -m\omega \hat{x}(0) \sin \omega t + \hat{p}(0) \cos \omega t$$

$$\langle X(t) \rangle = \sqrt{\frac{\hbar}{2m\omega}} (\langle a(t) \rangle + \langle a^\dagger(t) \rangle)$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left(\underbrace{d e^{-i\omega t}}_{d(t)} + \underbrace{d^* e^{+i\omega t}}_{d^*(t)} \right)$$

$$\langle X(t) \rangle = 2\sqrt{\frac{\hbar}{2m\omega}} \operatorname{Re}(d(t))$$

$$\langle P(t) \rangle = 2\sqrt{\frac{m\omega}{2}} \operatorname{Im}(d(t))$$

Si $d(0) = |d| e^{-i\phi_0}$

$$d(t) = |d| e^{-i(\omega t + \phi_0)}$$

$$d^*(t) = |d| e^{i(\omega t + \phi_0)}$$

h) e i) están después del (c).

e) Usamos el punto (h):

$$|d\rangle = e^{-\frac{|d|^2}{2}} \sum_n \frac{d^n}{\sqrt{n!}} |n\rangle$$

Si se mide H :

$$\operatorname{Prob}\left(\hbar\omega\left(n+\frac{1}{2}\right) \mid |d\rangle\right) = e^{-\frac{|d|^2}{2}} \frac{|d|^n}{n!}$$

Distrib.
de Poisson

$$\langle H \rangle = \hbar\omega |d|^2$$

$$(m) \quad \frac{\operatorname{Sdv}(N)}{N} \sim \frac{1}{|d|} \qquad \frac{\operatorname{Sdv}(H)}{H} \sim \frac{1}{|d|}$$

Si $|d| \gg 1 \Rightarrow$ la incertidza relativa tiende a cero.

Gua 6: Oscilaciones armónicas

Conto. PA

(K) Probar que $|\alpha(t)\rangle = U(t,0)|\alpha\rangle$ es un estado coherente, hallar $\alpha(t)$.

$$a|\alpha(t)\rangle = aU(t,0)|\alpha\rangle$$

$$\uparrow = U(t,0)U^\dagger(t,0)$$

$$= U(t,0) \underbrace{U^\dagger(t,0)aU(t,0)}_{a(t) = e^{-i\omega t}a} |\alpha\rangle$$

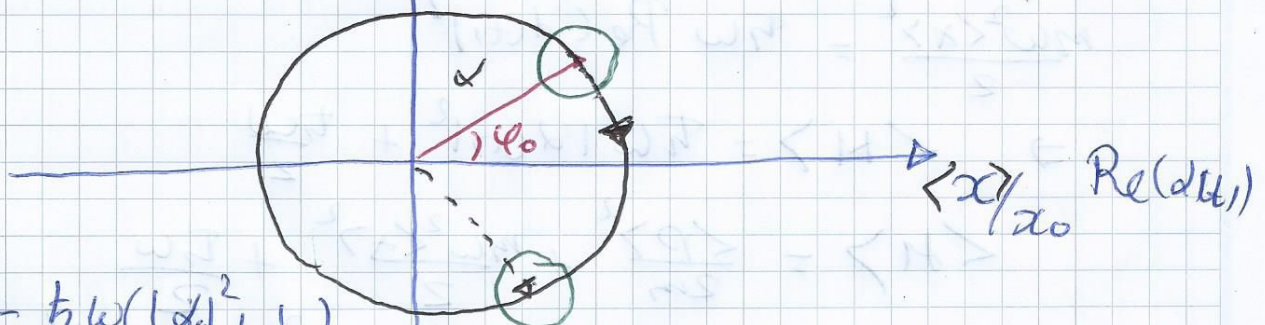
$$= U(t,0) \cdot e^{-i\omega t} a |\alpha\rangle$$

$$a|\alpha(t)\rangle = \alpha(t)|\alpha(t)\rangle$$

$$\text{con } |\alpha(t)\rangle = e^{-i\omega t} |\alpha\rangle$$

Todos los cálculos previos con $|\alpha\rangle$ valen para $|\alpha(t)\rangle$ cambiando $\alpha \rightarrow \alpha e^{-i\omega t} = \alpha(t)$

$$\langle P \rangle / p_0 = \sin(\alpha(t))$$



$$\langle H \rangle = \hbar\omega \left(|\alpha|^2 + \frac{1}{2} \right)$$

No dep. del tiempo

incertidza mínima indep. del tiempo

Si $|\alpha|$ es muy grande ($|\alpha| \gg 1$)
 el comportamiento es muy similar al
 clásico, sus valores medios oscilan
 y la incertidumbre relativa es muy chica.
 [Esto no pasa en los autoestados $|n\rangle$]
 cuyo valor medio es $\langle x \rangle = \langle p \rangle = 0$

(i) Sea $|\alpha\rangle = \sum_n C_n |n\rangle \Rightarrow a|\alpha\rangle = \alpha|\alpha\rangle$
 $\sum_n C_n a|n\rangle = \sum_n \alpha C_n |n\rangle$
 $C_n = \alpha \frac{C_{n-1}}{\sqrt{n}} \iff \sum_n C_n \sqrt{n} |n-1\rangle = \sum_n \alpha C_n |n\rangle$

$C_0 = 1 \Rightarrow C_n = \frac{\alpha^n}{\sqrt{n!}}$

$|\alpha\rangle = N \sum_n \frac{\alpha^n}{\sqrt{n!}} |n\rangle$

$\langle \alpha | \alpha \rangle = 1 \Rightarrow N^2 = \sum_n \frac{|\alpha|^{2n}}{n!} \Rightarrow N = e^{-\frac{|\alpha|^2}{2}}$

$|\alpha\rangle = e^{-\frac{|\alpha|^2}{2}} \sum_n \frac{\alpha^n}{\sqrt{n!}} |n\rangle$
 $|B\rangle = e^{-\frac{|B|^2}{2}} \sum_n \frac{B^n}{\sqrt{n!}} |n\rangle$

$\langle B | \alpha \rangle = e^{-\frac{|B|^2 - |B\alpha|}{2}} \sum_n \frac{(B\alpha)^n}{n!}$

$\langle B | \alpha \rangle = e^{-\frac{1}{2} [|B|^2 + |B\alpha| - 2B\alpha]}$

(ii) $\langle H \rangle = \frac{1}{2} \hbar \omega (|\alpha(t)|^2 + \frac{1}{2})$

$\langle p \rangle = 2 \sqrt{\frac{\hbar m \omega}{2}} \text{Im} \alpha(t)$

$\langle x \rangle = 2 \sqrt{\frac{\hbar}{2m\omega}} \text{Re} \alpha(t)$

$\Rightarrow \frac{\langle p \rangle^2}{2m} = \hbar \omega \text{Im}(\alpha(t))^2$

$\frac{m\omega^2 \langle x \rangle^2}{2} = \hbar \omega \text{Re}(\alpha(t))^2$

$\Rightarrow \langle H \rangle = \hbar \omega |\alpha(t)|^2 + \frac{\hbar \omega}{2}$

$\langle H \rangle = \frac{\langle p \rangle^2}{2m} + \frac{m\omega^2 \langle x \rangle^2}{2} + \frac{\hbar \omega}{2}$

Si $\langle H \rangle \gg \hbar \omega \Rightarrow \langle H \rangle \approx \frac{\langle p \rangle^2}{2m} + \frac{m\omega^2 \langle x \rangle^2}{2}$
 $|\alpha| \gg 1$

relación
de Heisenberg

Guió 6: Oscilador armónico

[P5] Operador de desplazamiento en el espacio de fases.

Motivación: del punto (f) **[P4]** podemos concluir que a menos de una fase:

$$|d\rangle = e^{i\frac{\langle p \rangle x - i\frac{\langle x \rangle p}{\hbar}}{\hbar}} |0\rangle$$

$$i\frac{\langle p \rangle x}{\hbar} = i\frac{2\sqrt{\frac{\hbar m \omega}{2}}}{\hbar} \cdot \sqrt{\frac{\hbar}{2m\omega}} (a + a^\dagger) \operatorname{Im}(d)$$

$$-i\frac{\langle x \rangle p}{\hbar} = -i\frac{2\sqrt{\frac{\hbar}{2m\omega}}}{\hbar} \cdot \sqrt{\frac{\hbar m \omega}{2}} \frac{(a - a^\dagger) \operatorname{Re}(d)}{i}$$

$$= i(a + a^\dagger) \operatorname{Im}(d) + (a - a^\dagger) \operatorname{Re}(d)$$

$$= a^\dagger d - a d^*$$

$$|d\rangle = e^{\underbrace{(a^\dagger d - a d^*)}_{D(d)}} |0\rangle$$

$D(d)$ es el operador de desplazamiento en el espacio de fases.

Desplaza en $\langle x \rangle = \frac{2\sqrt{\frac{\hbar}{2m\omega}} \operatorname{Re} d}{2}$ y en $\langle p \rangle = \frac{2\sqrt{\frac{\hbar m \omega}{2}} \operatorname{Im} d}{2}$.

$$(a) \quad D(d) = e^{a^\dagger d - a d^*} = e^A$$

$$D^\dagger(d) = e^{a d^* - a^\dagger d} = e^{A^\dagger} = e^{-A}$$

$$(b) \quad D(d) D^\dagger(d) = D^\dagger(d) D(d) = \mathbb{1}$$

$$D^\dagger(\alpha) = D(-\alpha)$$

$D(\alpha)$ of unitario.

$$\begin{aligned} (b) \quad D(\alpha+B) &= e^{(\alpha+B)a^\dagger - (\alpha+B)^*a} \\ &= e^{(\alpha a^\dagger - \alpha^* a) + (B a^\dagger - B^* a)} \\ &= e^{A+B} \end{aligned}$$

$$\begin{aligned} [A, B] &= [\alpha a^\dagger - \alpha^* a, B a^\dagger - B^* a] \\ &= \alpha B^* - \alpha^* B = 2i \operatorname{Im}(\alpha B^*) \quad \square \end{aligned}$$

$$[A, [A, B]] = [B, [A, B]] = 0$$

aplica BCH: $e^{A+B} = e^A e^B e^{-\frac{1}{2}[A, B]}$

$$D(\alpha+B) = D(\alpha) D(B) e^{-i \operatorname{Im}(\alpha B^*)}$$

$$(c) \quad D^\dagger(\alpha) Q D(\alpha) = e^A a e^{-A} \quad -A = \alpha a^\dagger - \alpha^* a$$

para: $[A, a] = [\alpha a^\dagger - \alpha^* a, a] = -\alpha \underbrace{[a^\dagger, a]}_{-1} = +\alpha$

$$\Rightarrow [A, [A, a]] = [a, [A, a]] = 0 \quad = +\alpha$$

$$D^\dagger(\alpha) a D(\alpha) = a + \frac{[A, a]}{\alpha} + \frac{[A, [A, a]]}{2! \alpha^2} + \dots$$

[P17] Ex 2.2

$$\circ \quad D^\dagger(\alpha) a D(\alpha) = a + \alpha$$

$$\Rightarrow D^\dagger(\alpha) a^\dagger D(\alpha) = a^\dagger + \alpha^* \quad (\text{da mesma})$$

$$D^\dagger(\alpha) X D(\alpha) = \sqrt{\frac{\hbar}{2m\omega}} (a + \alpha + a^\dagger + \alpha^*) = X + 2\sqrt{\frac{\hbar}{2m\omega}} \operatorname{Re}(\alpha)$$

$$D^\dagger(\alpha) P D(\alpha) = \sqrt{\frac{\hbar m\omega}{2}} \frac{1}{i} (a + \alpha - a^\dagger - \alpha^*) = P + 2\sqrt{\frac{\hbar m\omega}{2}} \operatorname{Im}(\alpha)$$

Guía 6: Oscilador armónico

Cont. [P5]

(d) Probar que $|\alpha\rangle = D(\alpha)|0\rangle$ es autoestado de a : (aniquilación) (bajada)

$$\begin{aligned} a|\alpha\rangle &= aD(\alpha)|0\rangle \\ &= \underbrace{D(\alpha)}_{\neq 0} \underbrace{D^\dagger(\alpha)}_{\neq 0} a D(\alpha)|0\rangle \\ &= D(\alpha) (a + \alpha)|0\rangle \quad a|0\rangle = 0 \\ &= \alpha D(\alpha)|0\rangle = \alpha|\alpha\rangle \end{aligned}$$

$\therefore |\alpha\rangle = D(\alpha)|0\rangle$ es un estado coherente.

$$(e) D(\alpha) = e^{\alpha a^\dagger - \alpha^* a} = e^{\alpha a^\dagger} e^{-\alpha^* a} e^{-\frac{|\alpha|^2}{2}}$$

$$[\alpha a^\dagger, \alpha^* a] = -|\alpha|^2 [a, a^\dagger] = -|\alpha|^2$$

$$|\alpha\rangle = D(\alpha)|0\rangle = e^{-\frac{|\alpha|^2}{2}} e^{\alpha a^\dagger} \underbrace{e^{-\alpha^* a}}_{|0\rangle} |0\rangle$$

$$\therefore |\alpha\rangle = e^{-\frac{|\alpha|^2}{2}} e^{\alpha a^\dagger} |0\rangle$$

$$|\alpha\rangle = e^{-\frac{|\alpha|^2}{2}} \sum_n \frac{(\alpha a^\dagger)^n}{n!} |0\rangle$$

$$\text{pero: } a^n |0\rangle = \sqrt{n!} |n\rangle$$

$$|\alpha\rangle = e^{-\frac{|\alpha|^2}{2}} \sum_n \frac{\alpha^n}{\sqrt{n!}} |n\rangle$$

f) Si $\text{Im}(\alpha) = 0 \Rightarrow$ no se desplaza en momento

$$D^\dagger(\alpha) X D(\alpha) = X + \underbrace{\sqrt{\frac{\hbar}{2m\omega}}}_{\Delta x} 2 \text{Re} \alpha$$

$\therefore D(\alpha)$ es el operador de desplazamiento.

$$D(\alpha) = e^{-i \frac{p \Delta x}{\hbar}}$$

\bullet Si $\text{Re}(\alpha) = 0 \Rightarrow$ no se desplaza en posición

$$D^\dagger(\alpha) P D(\alpha) = P + \underbrace{\sqrt{\frac{\hbar m \omega}{2}}}_{\Delta p} 2 \text{Im} \alpha.$$

$$D(\alpha) = e^{i \frac{x \Delta p}{\hbar}}$$

\bullet En general desplaza en posición y en momento.

$$(g) \langle \alpha | X | \alpha \rangle = \langle 0 | D^\dagger(\alpha) X D(\alpha) | 0 \rangle$$

$$= \langle 0 | X + 2 \sqrt{\frac{\hbar}{2m\omega}} \text{Re} \alpha | 0 \rangle =$$

$$\therefore \langle \alpha | X | \alpha \rangle = 2 \sqrt{\frac{\hbar}{2m\omega}} \text{Re} \alpha.$$

$$\langle \alpha | P | \alpha \rangle = \langle 0 | D^\dagger(\alpha) P D(\alpha) | 0 \rangle$$

$$= \langle 0 | P + 2 \sqrt{\frac{\hbar m \omega}{2}} \text{Im} \alpha | 0 \rangle$$

$$\therefore \langle \alpha | P | \alpha \rangle = 2 \sqrt{\frac{\hbar m \omega}{2}} \text{Im} \alpha$$

donde se usó $\langle 0 | X | 0 \rangle = 0 = \langle 0 | P | 0 \rangle$

$$\langle \alpha | X^2 | \alpha \rangle = \langle 0 | \underbrace{D^\dagger(\alpha) X D(\alpha)}_{X + \langle X \rangle} \underbrace{D^\dagger(\alpha) X D(\alpha)}_{X + \langle X \rangle} | 0 \rangle$$

$$= \langle 0 | X^2 + 2X \langle X \rangle + \langle X \rangle^2 | 0 \rangle$$

$$= \langle 0 | X^2 | 0 \rangle + \langle X \rangle^2$$

$$\text{Var}(X) = \langle \alpha | X^2 | \alpha \rangle - (\langle \alpha | X | \alpha \rangle)^2 = \underbrace{\langle 0 | X^2 | 0 \rangle}_{\frac{\hbar}{2m\omega}}$$

$$\text{Var}(P) = \underbrace{\langle 0 | P^2 | 0 \rangle}_{\frac{\hbar m \omega}{2}}$$

$$\frac{\hbar}{2m\omega}$$