



Telemetría de bajo consumo para adquisición remota de datos fisiológicos

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Un poco de contexto: aves oscinas como modelo animal

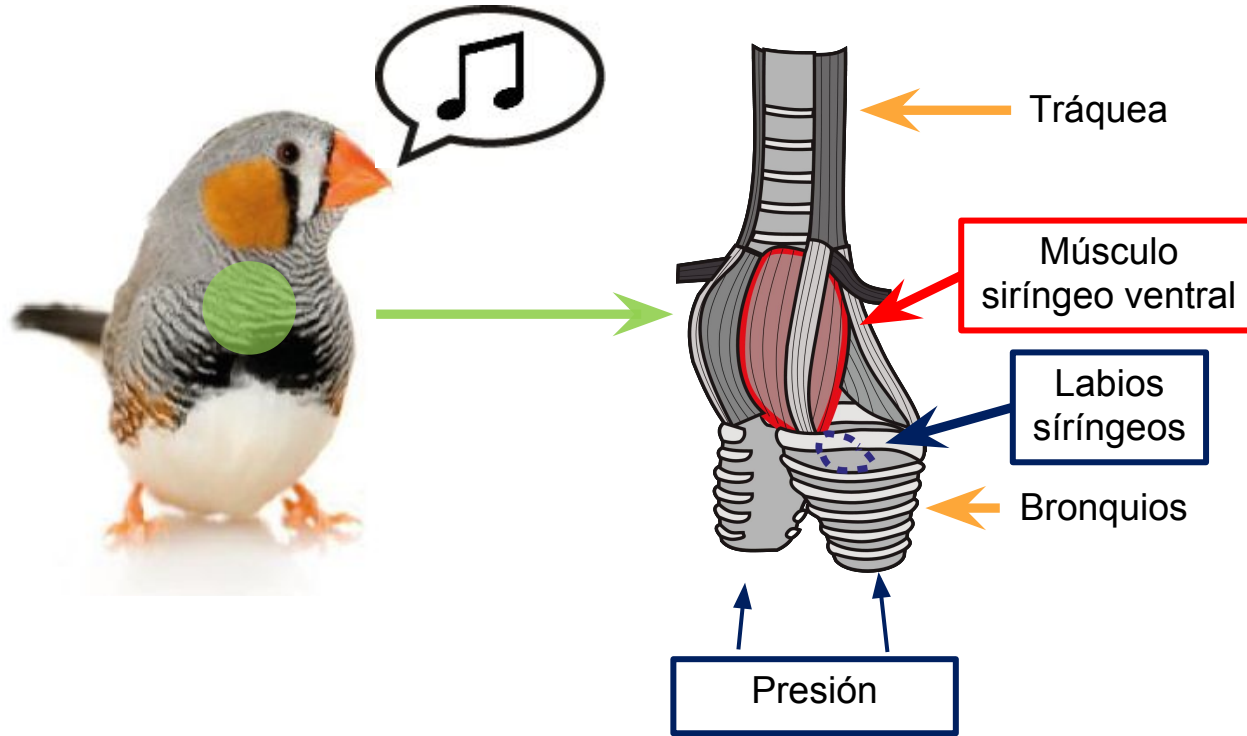
- Etapas de aprendizaje análogas a humanos
- Mecanismos de producción similares
- Especies campeonas para estudio de mecanismos de aprendizaje y producción vocal



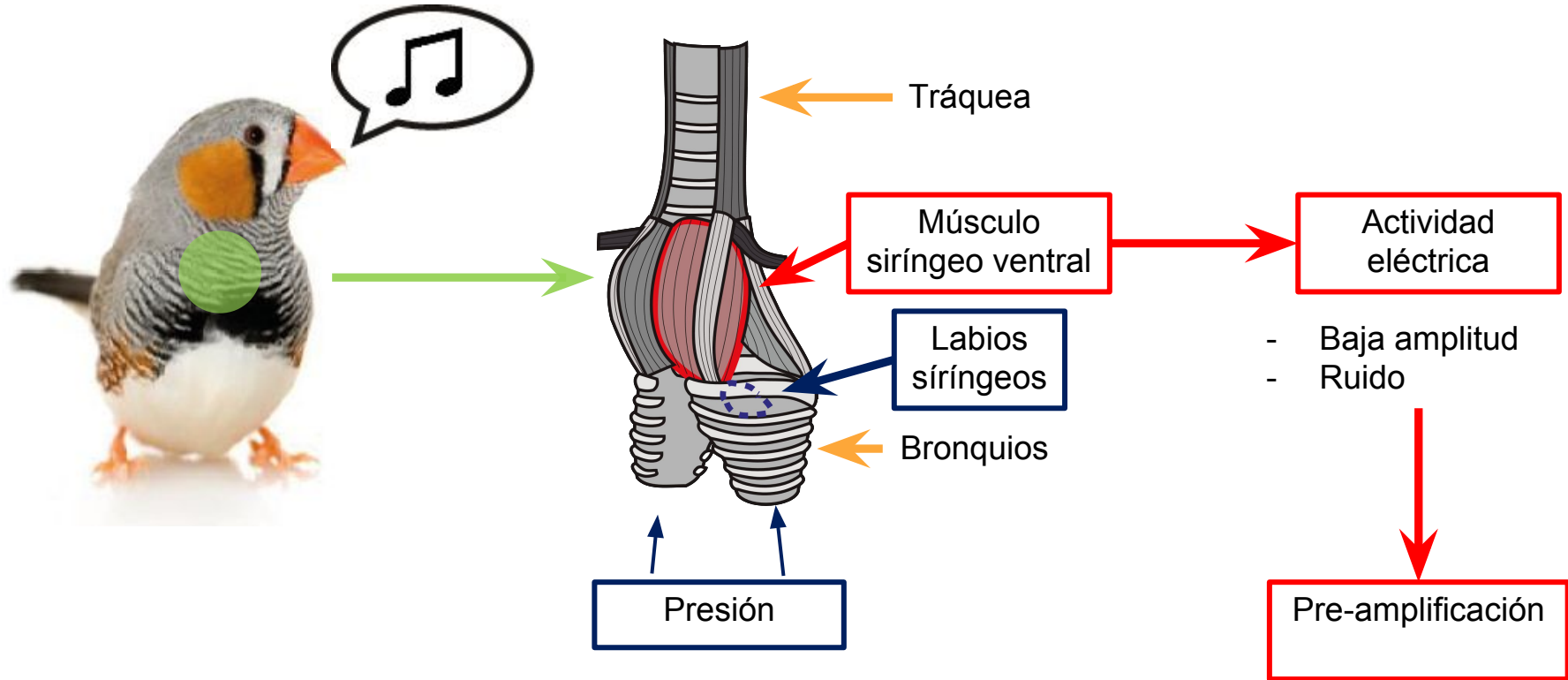
Un ejemplo de medición: electromiografía



Un ejemplo de medición: electromiografía

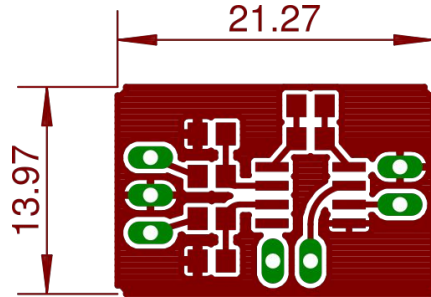


Un ejemplo de medición: electromiografía



El desafío: mediciones con animales libres

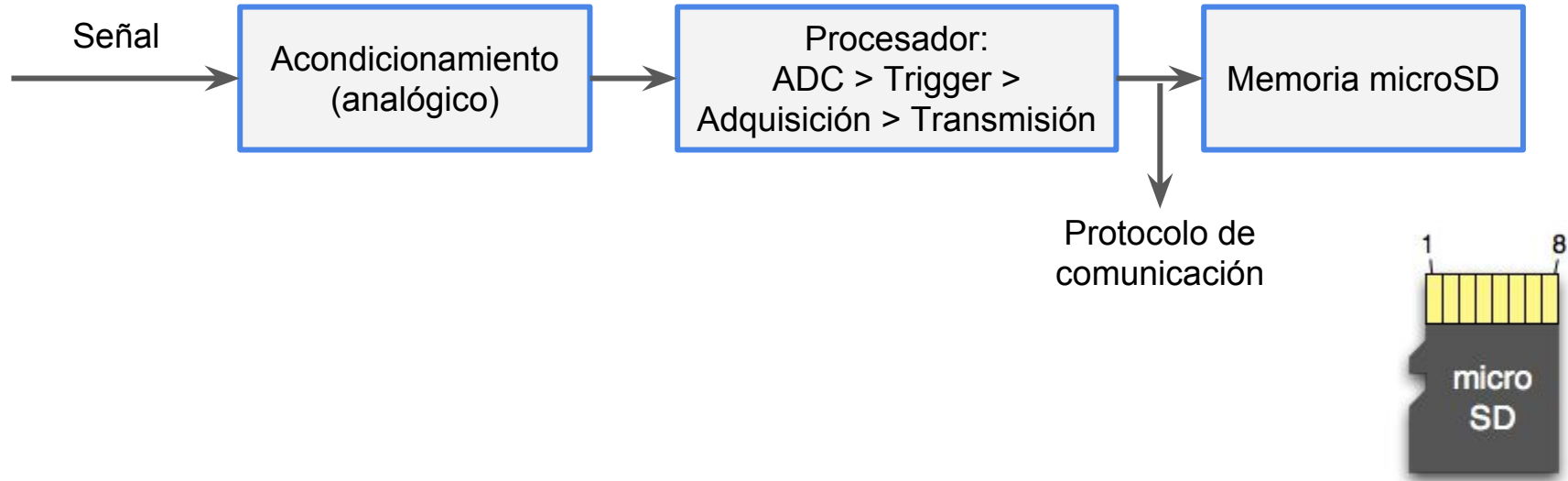
- Tamaño: debe ser portable ($\sim 1\text{cm} \times 2\text{cm}$)
- Peso: debe ser portable (debajo de 20% del peso)



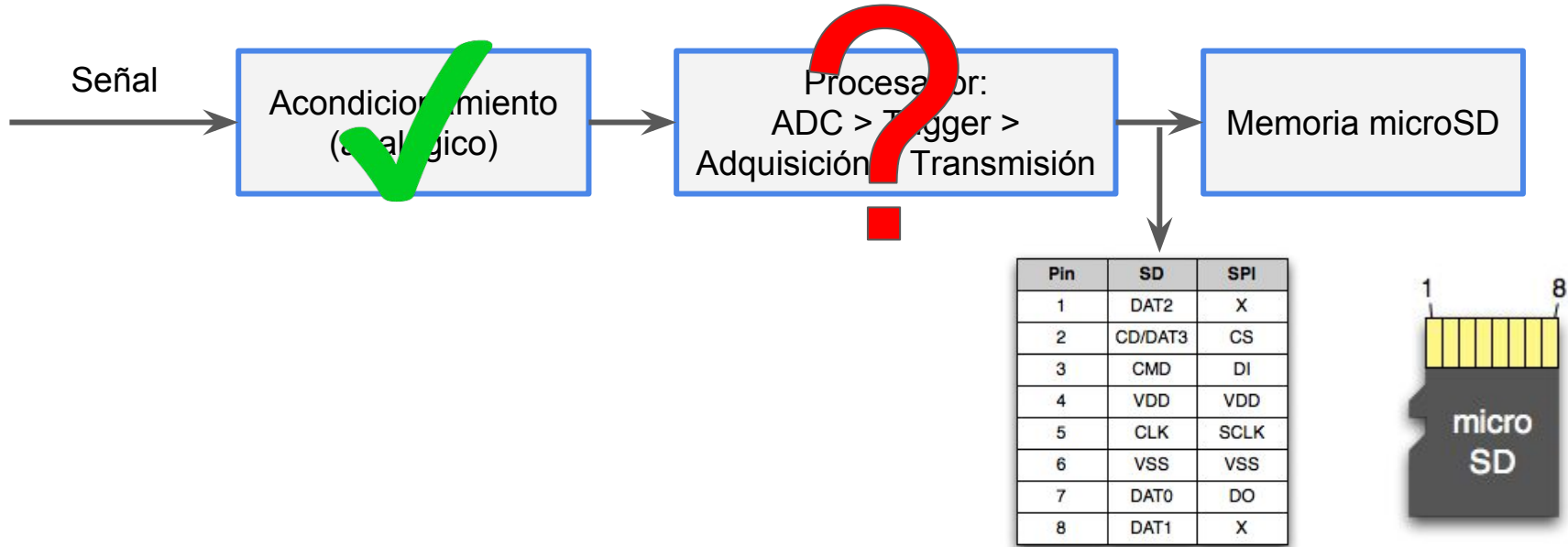
- Bajo consumo
- Autonomía (adquisición)



Propuesta: adquisición remota en microSD usando microprocesador



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Microprocesadores MSP430

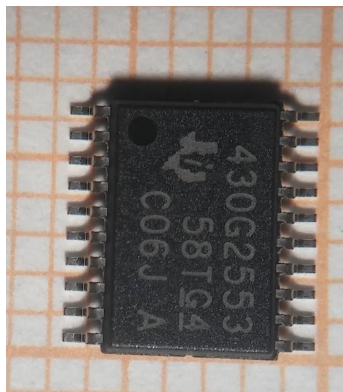


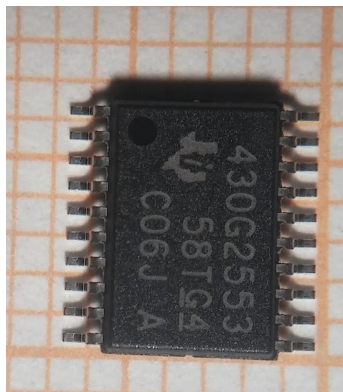
Table 1. Available Options⁽¹⁾⁽²⁾

Device	BSL	EEM	Flash (KB)	RAM (B)	Timer_A	COMP_A+ Channel	ADC10 Channel	USCI_A0, USCI_B0	Clock	I/O	Package Type
MSP430G2553IRHB32	1	1	16	512	2x TA3	8	8	1	LF, DCO, VLO	24	32-QFN
MSP430G2553IPW28										24	28-TSSOP
MSP430G2553IPW20										16	20-TSSOP
MSP430G2553IN20										16	20-PDIP

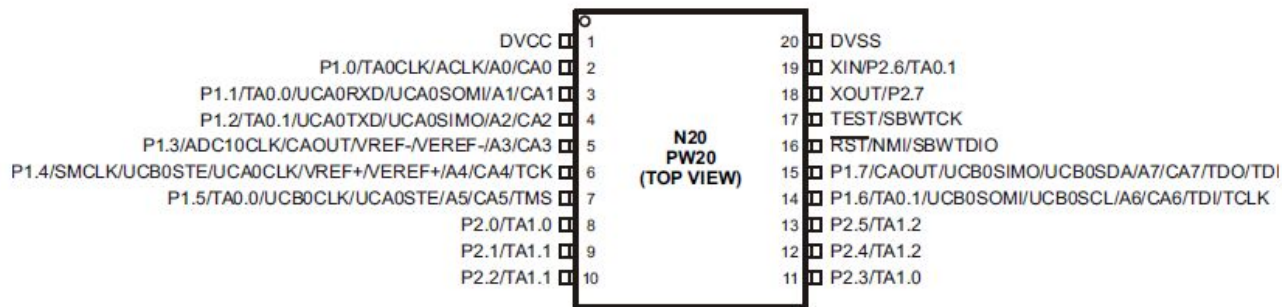
FEATURES

- Low Supply-Voltage Range: 1.8 V to 3.6 V
- Ultra-Low Power Consumption
 - Active Mode: 230 μ A at 1 MHz, 2.2 V
 - Standby Mode: 0.5 μ A
 - Off Mode (RAM Retention): 0.1 μ A
- Five Power-Saving Modes
- Ultra-Fast Wake-Up From Standby Mode in Less Than 1 μ s
- 16-Bit RISC Architecture, 62.5-ns Instruction Cycle Time
- Basic Clock Module Configurations
 - Internal Frequencies up to 16 MHz With Four Calibrated Frequency
 - Internal Very-Low-Power Low-Frequency (LF) Oscillator
 - 32-kHz Crystal
 - External Digital Clock Source
- Two 16-Bit Timer_A With Three Capture/Compare Registers
- Up to 24 Capacitive-Touch Enabled I/O Pins
- Universal Serial Communication Interface (USCI)
 - Enhanced UART Supporting Auto Baudrate Detection (LIN)
 - IrDA Encoder and Decoder
 - Synchronous SPI
 - I²C™
- On-Chip Comparator for Analog Signal Compare Function or Slope Analog-to-Digital (A/D) Conversion
- 10-Bit 200-kSPS Analog-to-Digital (A/D) Converter With Internal Reference, Sample-and-Hold, and Autoscan (See Table 1)
- Brownout Detector
- Serial Onboard Programming, No External Programming Voltage Needed, Programmable Code Protection by Security Fuse
- On-Chip Emulation Logic With Spy-Bi-Wire Interface
- Family Members are Summarized in Table 1
- Package Options

Microprocesadores MSP430



Device Pinout, MSP430G2x13 and MSP430G2x53, 20-Pin Devices, TSSOP and PDIP



NOTE: ADC10 is available on MSP430G2x53 devices only.

NAME	TERMINAL NO.			I/O	DESCRIPTION
	PW20, N20	PW28	RHB32		
P1.0/ TA0CLK/ ACLK/ A0 CA0	2	2	31	I/O	General-purpose digital I/O pin Timer0_A, clock signal TACLK input ACLK signal output ADC10 analog input A0 ⁽¹⁾ Comparator_A+, CA0 input



 **TEXAS
INSTRUMENTS**
MSP430



Hello world: blinking led

Ingredientes:

- 1) LED: output digital

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8.2.5 Function Select Registers PxSEL and PxSEL2

Port pins are often multiplexed with other peripheral module functions. See the device-specific data sheet to determine pin functions. Each PxSEL and PxSEL2 bit is used to select the pin function - I/O port or peripheral module function.

Table 8-1. PxSEL and PxSEL2

PxSEL2	PxSEL	Pin Function
0	0	I/O function is selected.
0	1	Primary peripheral module function is selected.
1	0	Reserved. See device-specific data sheet.
1	1	Secondary peripheral module function is selected.

8.2.2 Output Registers PxOUT

Each bit in each PxOUT register is the value to be output on the corresponding I/O pin when the pin is configured as I/O function, output direction, and the pullup/down resistor is disabled.

Bit = 0: The output is low

Bit = 1: The output is high

8.2.3 Direction Registers PxDIR

Each bit in each PxDIR register selects the direction of the corresponding I/O pin, regardless of the selected function for the pin. PxDIR bits for I/O pins that are selected for other functions must be set as required by the other function.

Bit = 0: The port pin is switched to input direction

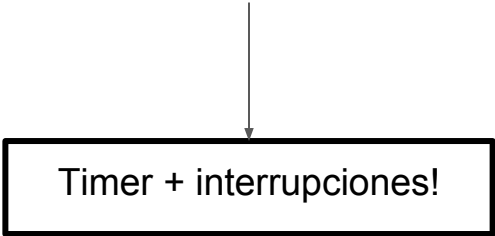
Bit = 1: The port pin is switched to output direction

Hello world: **blinking** led

Ingredientes:

- 1) LED: output digital
- 2) Timing: ¿cómo cuento tiempo?

`__delay_cycles(n);` ~ wait de python → Mala idea en general



Timer + interrupciones!

Interrupciones

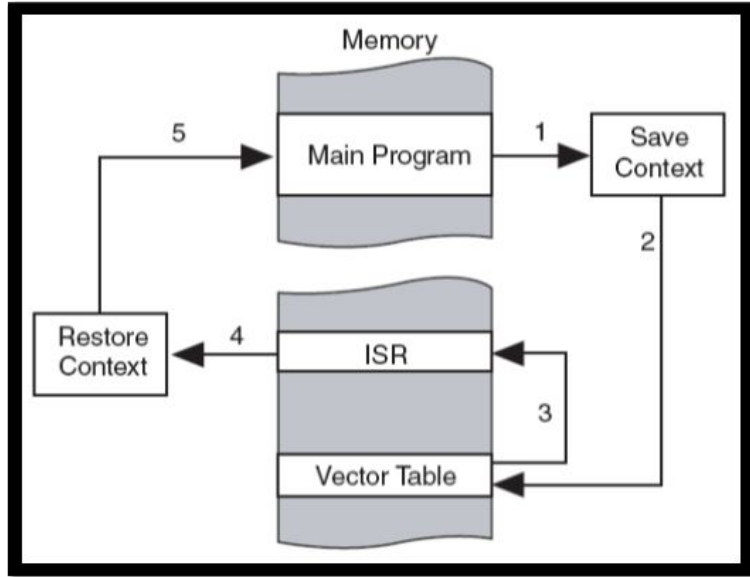


Table 5. Interrupt Sources, Flags, and Vectors

INTERRUPT SOURCE	INTERRUPT FLAG	SYSTEM INTERRUPT	WORD ADDRESS	PRIORITY
Power-Up External Reset Watchdog Timer+ Flash key violation PC out-of-range ⁽¹⁾	PORIFG RSTIFG WDTIFG KEYV ⁽²⁾	Reset	0FFFEh	31, highest
NMI Oscillator fault Flash memory access violation	NMIIFG OFIFG ACCVIFG ⁽²⁾⁽³⁾	(non)-maskable (non)-maskable (non)-maskable	0FFFCh	30
Timer1_A3	TA1CCR0 CCIFG ⁽⁴⁾	maskable	0FFFAh	29
Timer1_A3	TA1CCR2 TA1CCR1 CCIFG, TAIFG ⁽²⁾⁽⁴⁾	maskable	0FFF8h	28
Comparator_A+	CAIFG ⁽⁴⁾	maskable	0FFF6h	27
Watchdog Timer+	WDTIFG	maskable	0FFF4h	26
Timer0_A3	TA0CCR0 CCIFG ⁽⁴⁾	maskable	0FFF2h	25
Timer0_A3	TA0CCR2 TA0CCR1 CCIFG, TAIFG ⁽⁵⁾⁽⁴⁾	maskable	0FFF0h	24
USCI_A0/USCI_B0 receive USCI_B0 I2C status	UCA0RXIFG, UCB0RXIFG ⁽²⁾⁽⁵⁾	maskable	0FFEEh	23
USCI_A0/USCI_B0 transmit USCI_B0 I2C receive/transmit	UCA0TXIFG, UCB0TXIFG ⁽²⁾⁽⁶⁾	maskable	0FFECh	22
ADC10 (MSP430G2x53 only)	ADC10IFG ⁽⁴⁾	maskable	0FFEAh	21
			0FFE8h	20
I/O Port P2 (up to eight flags)	P2IFG.0 to P2IFG.7 ⁽²⁾⁽⁴⁾	maskable	0FFE6h	19
I/O Port P1 (up to eight flags)	P1IFG.0 to P1IFG.7 ⁽²⁾⁽⁴⁾	maskable	0FFE4h	18
			0FFE2h	17
			0FFE0h	16
See ⁽⁷⁾			0FFDEh	15
See ⁽⁸⁾			0FFDEh to 0FFC0h	14 to 0, lowest

Hello world: **blinking** led

12.3.1 TACTL, Timer_A Control Register

15	14	13	12	11	10	9	8
Unused						TASSELx	
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)
7	6	5	4	3	2	1	0
IDx		MCx		Unused	TACLx	TAIE	TAIFG
rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)	rw-(0)

Unused	Bits 15-10	Unused
TASSELx	Bits 9-8	Timer_A clock source select
	00	TACLK
	01	ACLK
	10	SMCLK
	11	INCLK (INCLK is device-specific and is often assigned to the inverted TBCLK) (see the device-specific data sheet)
IDx	Bits 7-6	Input divider. These bits select the divider for the input clock.
	00	/1
	01	/2
	10	/4
	11	/8
MCx	Bits 5-4	Mode control. Setting MCx = 00h when Timer_A is not in use conserves power.
	00	Stop mode: the timer is halted.
	01	Up mode: the timer counts up to TACCR0.
	10	Continuous mode: the timer counts up to 0FFFFh.
	11	Up/down mode: the timer counts up to TACCR0 then down to 0000h.
Unused	Bit 3	Unused
TACLx	Bit 2	Timer_A clear. Setting this bit resets TAR, the clock divider, and the count direction. The TACLx bit is automatically reset and is always read as zero.
TAIE	Bit 1	Timer_A interrupt enable. This bit enables the TAIFG interrupt request.
	0	Interrupt disabled
	1	Interrupt enabled
TAIFG	Bit 0	Timer_A interrupt flag
	0	No interrupt pending
	1	Interrupt pending

5.3.1 DCOCTL, DCO Control Register

7	6	5	4	3	2	1	0
DCOx			MODx				
rw-0	rw-1	rw-1	rw-0	rw-0	rw-0	rw-0	rw-0

DCOx	Bits 7-5	DCO frequency select. These bits select which of the eight discrete DCO frequencies within the range defined by the RSELx setting is selected.
MODx	Bits 4-0	Modulator selection. These bits define how often the $f_{\text{DCO}+1}$ frequency is used within a period of 32 DCOCLK cycles. During the remaining clock cycles (32-MOD) the f_{DCO} frequency is used. Not useable when DCOx = 7.

5.3.2 BCSCCTL1, Basic Clock System Control Register 1

7	6	5	4	3	2	1	0
XT2OFF	XTS ⁽¹⁾⁽²⁾	DIVAx		RSELx			
rw-(1)	rw-(0)	rw-(0)	rw-(0)	rw-0	rw-1	rw-1	rw-1

XT2OFF	Bit 7	XT2 off. This bit turns off the XT2 oscillator
	0	XT2 is on
	1	XT2 is off if it is not used for MCLK or SMCLK.
XTS	Bit 6	LFXT1 mode select.
	0	Low-frequency mode
	1	High-frequency mode
DIVAx	Bits 5-4	Divider for ACLK
	00	/1
	01	/2
	10	/4
	11	/8

RSELx	Bits 3-0	Range select. Sixteen different frequency ranges are available. The lowest frequency range is selected by setting RSELx = 0. RSEL3 is ignored when DCOR = 1.
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Conversor analógico digital de 10 bits (ADC10)

- 1) Registra señales y devuelve un número de 10 bits (y tengo que hacer algo con esto!)
- 2) Configurar inicio, reloj, referencia, rango, sample and hold time ...
- 3) Genera una interrupción cuando termina

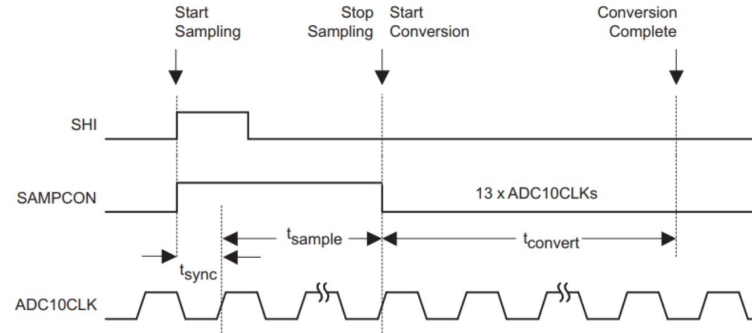
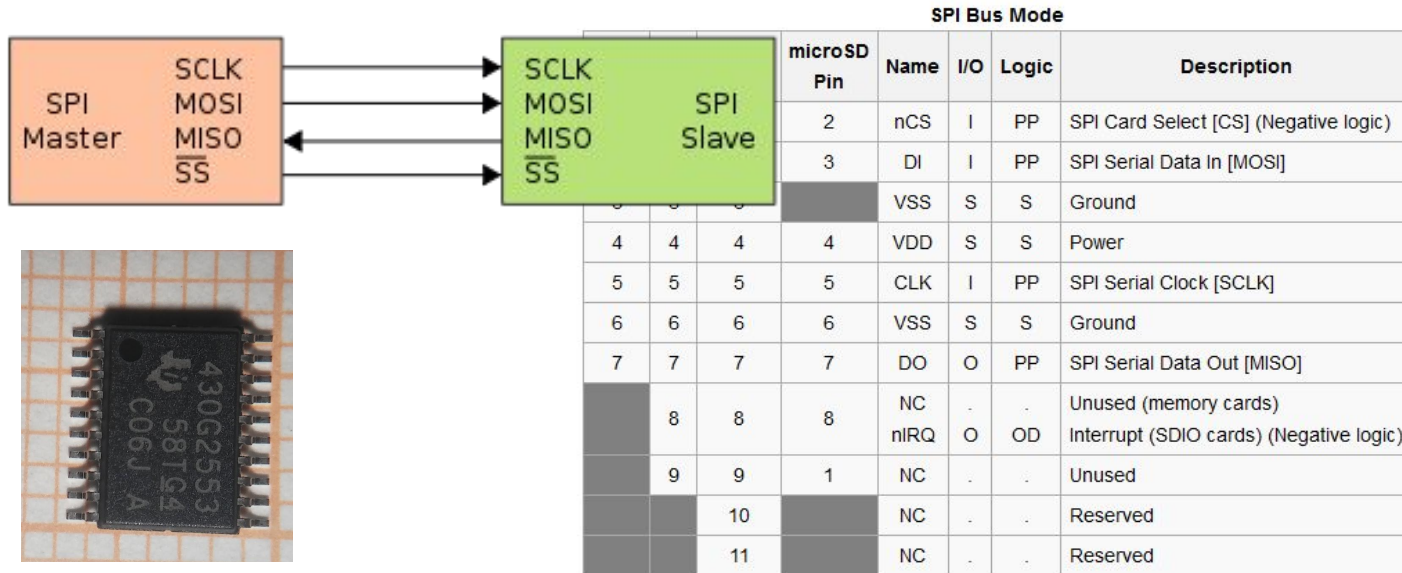


Figure 22-3. Sample Timing

Comunicación con la tarjeta microSD: protocolo SPI

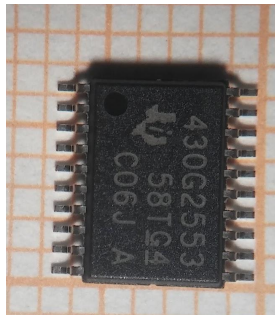
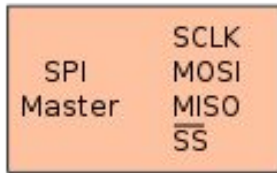
- **S**erial **P**eripheral Interface (SPI) es un protocolo de comunicación sincrónica.
- Soportado por SD (**S**ecure **D**igital)



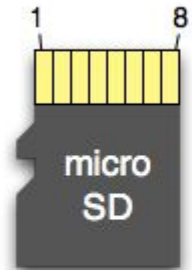
Comunicación con la tarjeta microSD: protocolo SPI

- **S**erial **P**eripheral Interface (SPI) es un protocolo de comunicación sincrónica.
- Soportado por

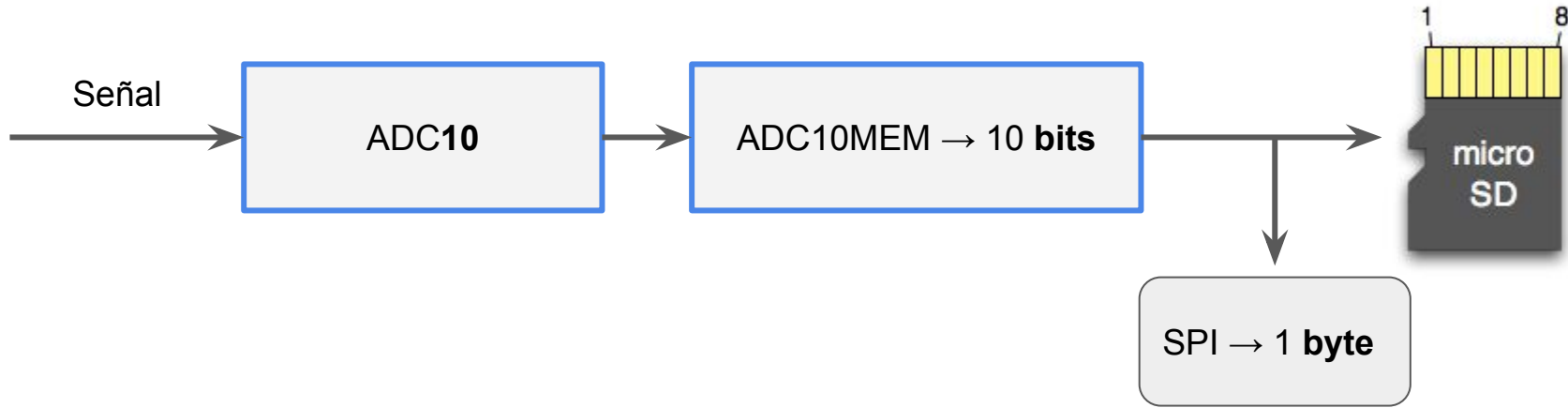
Alguien ya lo programó!



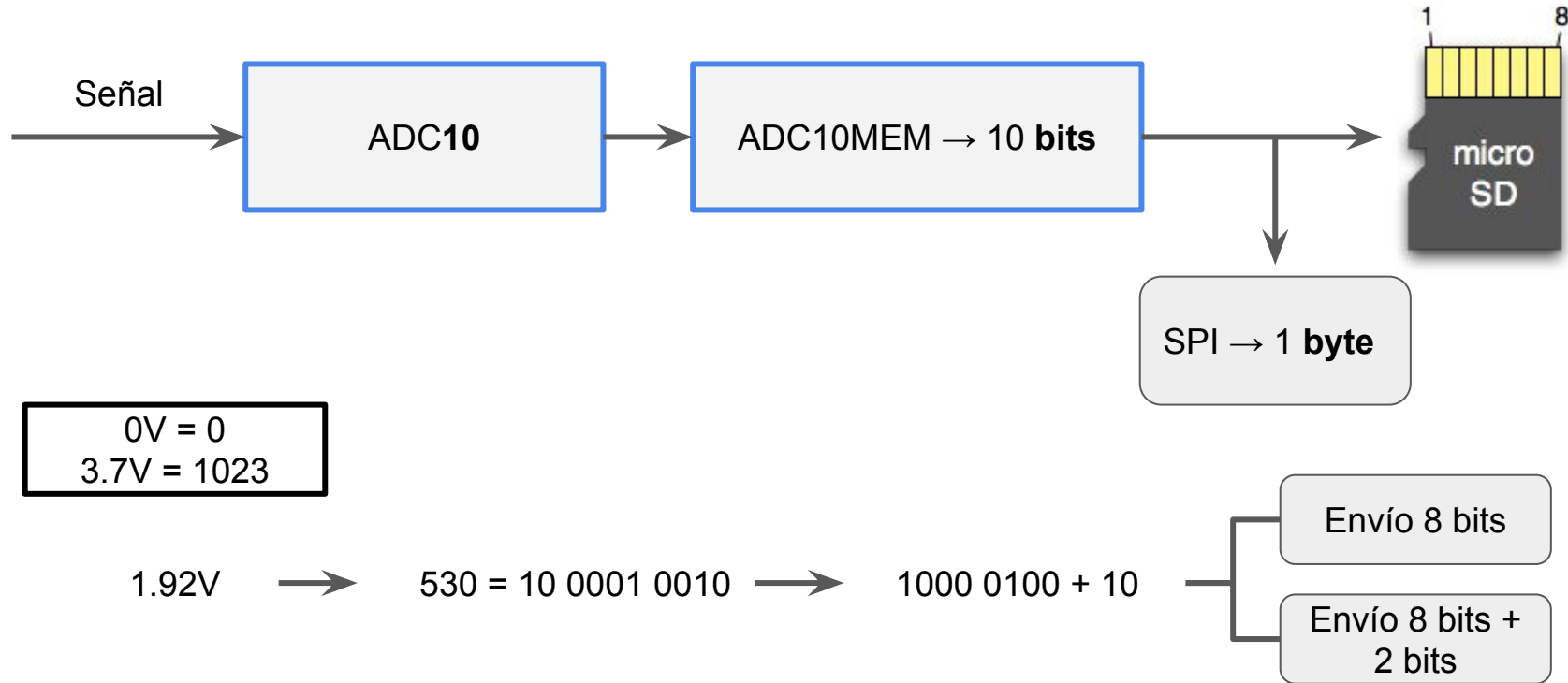
				Description			
				Card Select [CS] (Negative logic)			
				Serial Data In [MOSI]			
4	4	4	4	VDD	S	S	Power
5	5	5	5	CLK	I	PP	SPI Serial Clock [SCLK]
6	6	6	6	VSS	S	S	Ground
7	7	7	7	DO	O	PP	SPI Serial Data Out [MISO]
	8	8	8	NC	.	.	Unused (memory cards)
				nIRQ	O	OD	Interrupt (SDIO cards) (Negative logic)
	9	9	1	NC	.	.	Unused
		10		NC	.	.	Reserved
		11		NC	.	.	Reserved



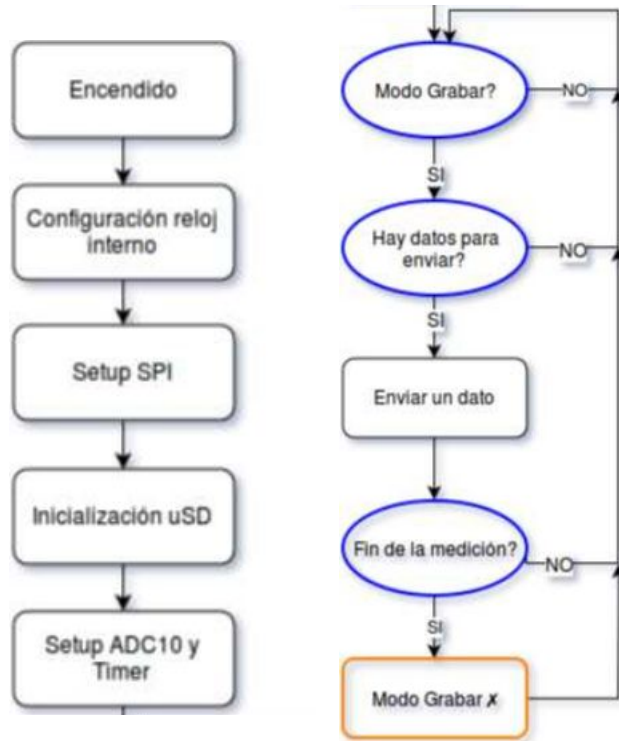
Resolución vs sampleo: 8 bits o 10 bits?



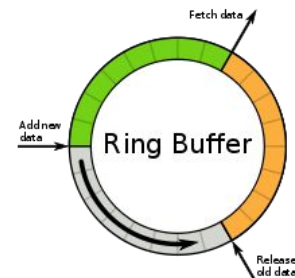
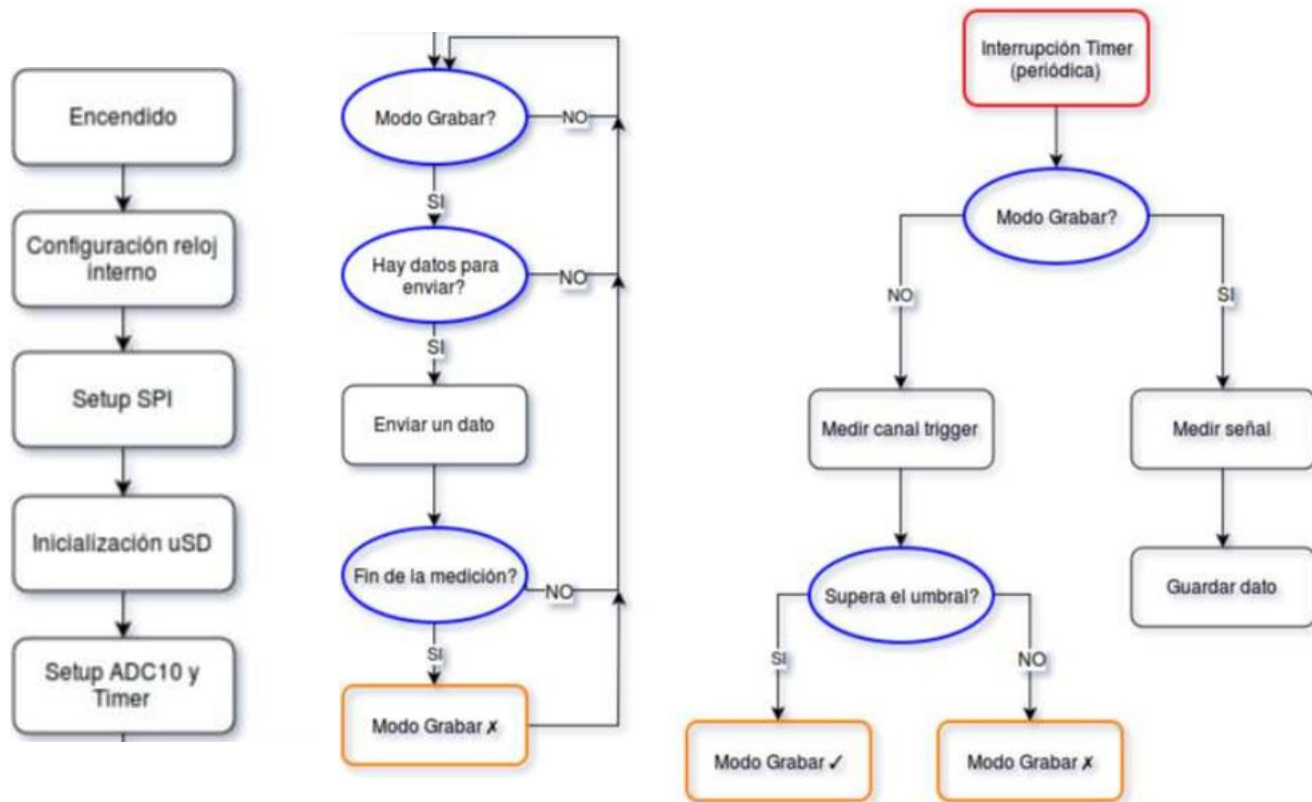
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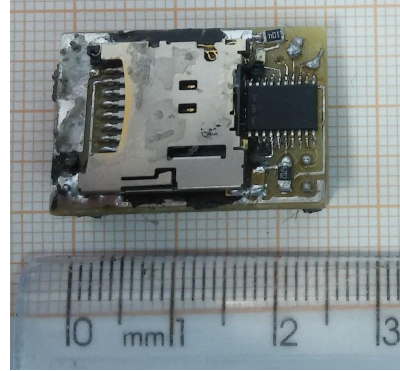
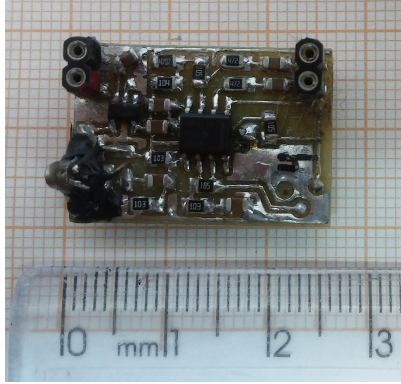
Flujo del programa



Flujo del programa



Problemas y desafíos



- Abrir archivos es muy lento: escribimos directamente en bytes
- Hay que saber cómo se grabaron los datos para poder leerlos
- Muy poco RAM: 512 bytes
- El manejo de la tarjeta limita la frecuencia de adquisición
- Tiempos muertos y lo que los fabricantes no dicen, ruidos y demás
- Baterías LiPo (de peso razonable) permiten ~7hs de adquisición continua

¡Gracias!