

# Exa 3: Control

P4) Usaremos:  $V(r) = -\frac{k}{r} + \frac{c}{2r^2}$  (1)

Partimos de las magnitudes conservadas:

$$\begin{cases} m\dot{r}^2 + \frac{l^2}{2mr^2} + V(r) = E & (2) \\ m\dot{\theta}^2 r^2 = l^2 & (3) \end{cases}$$

$$U(\theta) = \frac{1}{r(\theta)}$$

$$\frac{dU}{d\theta} = \frac{1}{r^2(\theta)} \cdot \frac{dr}{dt} \cdot \frac{dt}{d\theta}$$

$\underbrace{\hspace{10em}}_{\mu^2} \qquad \underbrace{\hspace{10em}}_{\frac{1}{\dot{\theta}} = \frac{m}{lU^2}}$

$$\Rightarrow \dot{r} = \frac{l}{m} \frac{dU}{d\theta} \quad (4)$$

(4) en (3):

$$\times \frac{2m}{l^2} \rightarrow \frac{l^2}{2m} \left( \frac{dU}{d\theta} \right)^2 + \frac{l^2}{2m} U^2 - kU + \frac{c}{2} U^2 = E$$

$$\left( \frac{dU}{d\theta} \right)^2 + \left( \sqrt{1 + \frac{mc}{l^2}} U - \frac{mk}{l^2 \sqrt{1 + \frac{mc}{l^2}}} \right)^2$$

$$= \frac{2mE}{l^2} + \frac{m^2 k^2}{(l^2 + mc) l^2}$$

o mejor:

$$\left(\frac{dU}{d\theta}\right)^2 + \left(\frac{\sqrt{1+mc}}{e^2}\right)^2 \left(\mu - \frac{mk}{e^2+mc}\right)^2 = \left(\frac{\sqrt{2E_m + \frac{m^2 k^2}{(e^2+mc)d^2}}}{e^2}\right)^2$$

Proposemos:

$$\mu = M_0 \cos[\alpha(\theta - \theta_0)] + \frac{mk}{e^2+mc}$$

$$\frac{d\mu}{d\theta} = -\alpha M_0 \sin[\alpha(\theta - \theta_0)]$$

$$\alpha^2 M_0^2 \sin^2[\alpha(\theta - \theta_0)] + \left(\frac{\sqrt{1+mc}}{e^2}\right)^2 M_0^2 \cos^2[\alpha(\theta - \theta_0)] = \left(\frac{\sqrt{2E_m + \frac{m^2 k^2}{(e^2+mc)d^2}}}{e^2}\right)^2$$

identificamos:

$$\alpha = \frac{\sqrt{1+mc}}{e^2}$$

$$M_0 = \frac{\sqrt{2E_m + \frac{m^2 k^2}{(e^2+mc)d^2}}}{e^2} \frac{1}{(e^2+mc)d^2} \frac{1}{\alpha}$$

Caso  $1 + \frac{mc}{e^2} > 0$

$$\frac{1}{r} = \frac{1}{\alpha} \frac{\sqrt{2E_m + \frac{m^2 k^2}{(e^2+mc)d^2}}}{e^2 (e^2+mc)d^2} \cos[\alpha(\theta - \theta_0)] + \frac{mk}{e^2+mc}$$

Si  $1 + \frac{mc}{e^2} < 0$   $\alpha \rightarrow i|\alpha|$

$$\frac{1}{r} = \frac{\sqrt{2E_m + \frac{m^2 k^2}{(e^2+mc)d^2}}}{\alpha^2 e^2 (e^2+mc)d^2} \cosh[|\alpha|(\theta - \theta_0)] + \frac{mk}{e^2+mc}$$