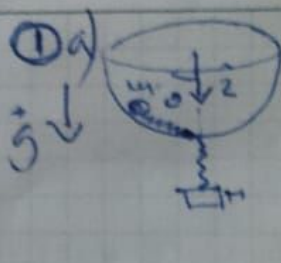


① a)  $T = \frac{M}{2} \dot{z}^2 + \frac{m}{2} R^2 (\dot{\theta}^2 + \sin^2 \theta \dot{\varphi}^2)$; $U = -m g R \cos \theta - M g z + \frac{k}{2} (R \theta + z)^2$

$$\mathcal{L} = \frac{m R^2}{2} (\dot{\theta}^2 + \sin^2 \theta \dot{\varphi}^2) + \frac{M}{2} \dot{z}^2 + m g R \cos \theta + M g z - \frac{k}{2} (R \theta + z)^2$$

b) Euler-Lagrange:

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\theta}} \right) - \frac{\partial \mathcal{L}}{\partial \theta} = m R^2 \ddot{\theta} - m R^2 \sin \theta \cos \theta \dot{\varphi}^2 + m g R \sin \theta + k R (R \theta + z) = 0 \quad (1)$$

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{\varphi}} \right) - \frac{\partial \mathcal{L}}{\partial \varphi} = \frac{d}{dt} (m R^2 \sin^2 \theta \dot{\varphi}) = 0 \quad (2) \rightsquigarrow m R^2 \sin^2 \theta \dot{\varphi} = cte$$

$$\frac{d}{dt} \left(\frac{\partial \mathcal{L}}{\partial \dot{z}} \right) - \frac{\partial \mathcal{L}}{\partial z} = M \ddot{z} - M g + k (R \theta + z) = 0 \quad (3)$$

¡en este caso, o también debe ser constante!

Si $z = d = cte \Rightarrow \ddot{z} = 0 \Rightarrow M g = k (R \theta_0 + d) \Rightarrow \frac{M g}{k} = R \theta_0 + d \Rightarrow d = \frac{M g}{k} - R \theta_0$

pero $\theta_0 \in [0, \pi/2] \Rightarrow d_{max} = \frac{M g}{k}$ y $d_{min} = \frac{M g}{k} - R \frac{\pi}{2}$ positivo por el dato del enunciado

\Rightarrow el bloque podrá permanecer en reposo si $z \in \left[\frac{M g}{k} - \frac{R \pi}{2}, \frac{M g}{k} \right]$

c) $\theta = \pi/4 \Rightarrow \dot{\theta} = \ddot{\theta} = 0$ ~~en este caso~~ $\sin \theta = \cos \theta = \frac{1}{\sqrt{2}}$

\Rightarrow (1) queda: $-\frac{m R^2}{2} \dot{\varphi}_0^2 + \frac{m g R}{\sqrt{2}} + k R \left(\frac{R \pi}{4} + z_0 \right) = 0 \quad (*)$

(Sabemos que $\dot{\varphi} = cte$ por la ec. (2) !!) \rightarrow (entonces $z = z_0 = cte$)

y (3) queda: $-M g + k \left(\frac{R \pi}{4} + z_0 \right) = 0 \Rightarrow z_0 = \frac{M g}{k} - \frac{R \pi}{4}$

(*) $\Leftrightarrow \frac{m R^2}{2} \omega_0^2 = \frac{m g R}{\sqrt{2}} + k R \left(\frac{M g}{k} \right)$ ($\| \text{entonces } \dot{\varphi}_0 \equiv \omega_0$)

$\Rightarrow \omega_0^2 = \frac{2 g}{\sqrt{2} R} + \frac{2 k M g}{m k R} = \left(\sqrt{2} + \frac{2 M}{m} \right) \frac{g}{R}$

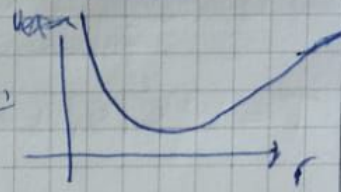
$\Rightarrow \omega_0 = \sqrt{\left(\sqrt{2} + \frac{2 M}{m} \right) \frac{g}{R}} \Rightarrow \tau = \frac{2 \pi}{\sqrt{\left(\sqrt{2} + \frac{2 M}{m} \right) \frac{g}{R}}} \sqrt{\frac{R}{g}}$

a) $\mathcal{L} = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\varphi}^2 + \dot{z}^2) - \beta \ln(r/r_0)$

$\frac{\partial \mathcal{L}}{\partial t} = 0 \Rightarrow H = E = \frac{m}{2} (\dot{r}^2 + r^2 \dot{\varphi}^2 + \dot{z}^2) + \beta \ln(r/r_0) = cte$
 $\rightarrow T=T_2$ y V NO DEPENDE DE LAS VELOCIDADES

$\frac{\partial \mathcal{L}}{\partial \varphi} = 0 \Rightarrow p_\varphi = m r^2 \dot{\varphi} = cte$; $\frac{\partial \mathcal{L}}{\partial z} = 0 \Rightarrow p_z = m \dot{z} = cte$

$\Rightarrow E = \frac{m \dot{r}^2}{2} + \frac{p_\varphi^2}{2 m r^2} + \frac{p_z^2}{2 m} + \beta \ln(r/r_0) = cte$



Caso $\lim_{r \rightarrow 0} V_{eff}(r) = \lim_{r \rightarrow \infty} V_{eff} = +\infty$; siempre hay dos puntos de retorno \rightarrow todas las órbitas son ligadas

b) Por lo anterior, necesariamente tiene un equilibrio \rightarrow 3 órbitas \rightarrow \exists órbitas con $\dot{r}=0$ $\forall t$ (son espirales en general.) \rightarrow $\dot{z}=cte$

$\frac{dV_{eff}}{dr} = -\frac{p_\varphi^2}{m r^3} + \frac{\beta}{r} = 0 \Leftrightarrow \frac{p_\varphi^2}{m} = \beta r^2 \Leftrightarrow \frac{p_\varphi^2}{m \beta} = r^2$

$\Leftrightarrow \frac{m^2 r_0^4 \omega_0^2}{m \beta} = r_0^2 \Leftrightarrow \frac{m r_0^2 \omega_0^2}{\beta} = 1 \Leftrightarrow \left(\frac{2\pi}{T_0}\right)^2 = \frac{\beta}{m r_0^2}$

$\Leftrightarrow \frac{T_0}{2\pi} = r_0 \sqrt{\frac{m}{\beta}} \Leftrightarrow T_0 = 2\pi \sqrt{\frac{m}{\beta}} r_0$ \rightarrow depende de la masa de la partícula \rightarrow no puede ser un potencial exclusivamente gravitatorio.

c) si $r \approx r_0 \Rightarrow V_{eff} \approx \frac{d^2 V_{eff}}{dr^2} \Big|_{r_0} (r-r_0)^2 + cte$

$\frac{d^2 V_{eff}}{dr^2} = \frac{3 p_\varphi^2}{m r^4} - \frac{\beta}{r^2} \Rightarrow \frac{d^2 V_{eff}}{dr^2} \Big|_{r_0} = \frac{3 m^2 r_0^4 \omega_0^2}{m r_0^4} - \frac{\beta}{r_0^2} = 2 m \omega_0^2$

$\Rightarrow E \approx \frac{m \dot{r}^2}{2} + \frac{2 m \omega_0^2}{2} (r-r_0)^2 \rightarrow$ osc. armónicas con $\omega_{rad} = \sqrt{\frac{2 m \omega_0^2}{m}}$

$\Rightarrow \omega_{rad} = \sqrt{2} \omega_0$ o bien $\frac{2\pi}{T_{rad}} = \sqrt{2} \frac{2\pi}{T_0} \Rightarrow T_{rad} = \frac{T_0}{\sqrt{2}}$

\therefore es imposible q' se creen $\left(\frac{T_{rad}}{T_0} \notin \mathbb{Q}\right)$.