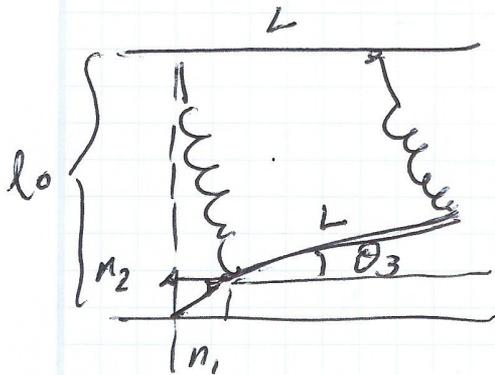


Pequeños Oscilaciones



$$n_3 = L\theta_3$$

$$2k(l_0 - a) = mg$$

$$l_0 = a + \frac{mg}{2k}$$

$$J_{cm} = \frac{mL^2}{12}$$

Tomamos $a=0$

$$n_3 = L\theta_3$$

$$x_{cm} = n_1 + \frac{L}{2}\cos\theta_3$$

$$y_{cm} = n_2 + \frac{L}{2}\sin\theta_3$$

$$T = \frac{m}{2} (\dot{n}_1^2 + (\dot{n}_2 + \dot{n}_3)^2) + \frac{m}{24} \dot{n}_3^2$$

$$V = \frac{k}{2} (n_2^2 + n_1^2) + \frac{k}{2} (n_2 + n_3)^2 + \frac{k}{2} n_1^2$$

3GL

Equilibrio: $n_1 = n_2 = \theta_3 = 0$

$$x_1 = n_1 \quad y_1 = n_2$$

$$x_2 = n_1 + L\cos\theta_3$$

$$y_2 = n_2 + L\sin\theta_3$$

$$T = \frac{m}{2} (\dot{x}_{cm}^2 + \dot{y}_{cm}^2) + \frac{I}{2} \dot{\theta}_3^2$$

$$V = \frac{k}{2} [(l_0 - n_2)^2 + n_1^2] + \frac{k}{2} [(l_0 - n_2 - L\sin\theta_3)^2 + (L\cos\theta_3 + n_1 - L)^2] - mg \left[l_0 - n_2 - \frac{L}{2}\sin\theta_3 \right]$$

$$\dot{x}_{cm} = \dot{n}_1 - \frac{L}{2}\sin\theta_3 \dot{\theta}_3$$

$$\dot{y}_{cm} = \dot{n}_2 + \frac{L}{2}\cos\theta_3 \dot{\theta}_3$$

$$\pi = m \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1/2 \\ 0 & 1/2 & 1/3 \end{pmatrix}$$

$$V = k \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

i) n_1 : desacoplado. $\vec{a}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \rightarrow n_2 = 0$
 $\rightarrow \theta_3 = 0.$

es auto vector con frecuencia!

$$\omega_1 = \sqrt{\frac{2k}{m}} = \sqrt{\frac{g}{l_0}}$$

Movimiento horizontal.

ii) Problema $\vec{a}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ Movimiento vertical.

$$V\vec{a}_2 = \omega^2 \pi \vec{a}_2 \Rightarrow V\vec{a}_2 = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix} \quad \pi \vec{a}_2 = \begin{pmatrix} 0 \\ 1 \\ 1/2 \end{pmatrix}$$

$$\Rightarrow \omega_2^2 = \frac{2k}{m} \Rightarrow \omega_2 = \sqrt{\frac{2k}{m}}$$

resortes en paralelo suman sus k 's.

iii) Problema $\vec{a}_3 = \begin{pmatrix} 0 \\ 1 \\ -2 \end{pmatrix}$ desliza por el eje (solo rota)

$$V\vec{a}_3 = \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix} \quad \pi \vec{a}_3 = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow \omega_3 = \sqrt{\frac{6k}{m}}$$

Equilibrio:

$$\frac{\partial V}{\partial n_1} = kn_1 + k(L \cos \theta_3 + n_1 - L) = 0 \quad (1)$$

$$\frac{\partial V}{\partial n_2} = -k(l_0 - n_2) - k(l_0 - n_2 - L \sin \theta_3) + mg = 0 \quad (2)$$

$$\frac{dV}{d\theta_3} = -kL(l_0 - n_2 - L \sin \theta_3) \cos \theta_3 - kL \sin \theta_3 (L \cos \theta_3 + n_1 - L) + \frac{mgL}{2} \cos \theta_3 = 0 \quad (3)$$

Si $\theta_3 = 0$, de (1) $n_1 = 0$

de (2) Si $n_2 = 0 \Rightarrow 2kl_0 = mg$
(condición de equilibrio)

de (3) Si $l_0 = \frac{mg}{2k}$ se satisface.

$$\frac{\partial^2 V}{\partial n_1^2} = 2k, \quad \frac{\partial^2 V}{\partial n_2^2} = 2k, \quad \frac{\partial^2 V}{\partial \theta_3^2} =$$

$$\frac{\partial^2 V}{\partial \theta_3^2} = kL^2 \cos \theta_3 \Big|_{\theta_3=0} + \frac{mgL}{2} \sin 2\theta_3 \Big|_{\theta_3=0} = kL^2$$

$$\frac{\partial^2 V}{\partial n_2 \partial n_1} = 0 = \frac{\partial^2 V}{\partial \theta_3 \partial n_1} = -kL \sin \theta_3 \Big|_{\theta_3=0} = 0$$

$$\frac{\partial^2 V}{\partial \theta_3 \partial n_2} = kL \cos \theta_3 \Big|_{\theta_3=0} = kL = \frac{\partial^2 V}{\partial n_2 \partial \theta_3}$$