Física de Semiconductores

Lección 8

Beyond free electrons: pseudopotentials

• We want to calculate $U_{K} = \frac{1}{v_{c}} \int d\mathbf{r} V(\mathbf{r}) e^{-i\mathbf{K}\cdot\mathbf{r}}$ We assume $V(\mathbf{r}) = \sum_{i} V_{j}(\mathbf{r})$ and if we define new potentials centered at each atom in the unit cell

$$V(\mathbf{r}) = \sum_{j} U_{j}(\mathbf{r} - \mathbf{a}_{j})$$

$$\mathbf{SO} \qquad U_{K} = \frac{1}{v_{c}} \int_{\text{unit cell}} d\mathbf{r} \left[\sum_{j} U_{j}(\mathbf{r} - \mathbf{d}_{j}) \right] e^{-i\mathbf{K}\cdot\mathbf{r}}$$

$$= \frac{1}{v_{c}} \sum_{j} e^{-i\mathbf{K}\cdot\mathbf{d}_{j}} \int_{\text{unit cell}} d\mathbf{r}' U_{j}(\mathbf{r}') e^{-i\mathbf{K}\cdot\mathbf{r}'} = \sum_{j} e^{-i\mathbf{K}\cdot\mathbf{d}_{j}} U_{jK}$$

Two atom cells

• For a two atom cell, I can always choose $d_A = -d_B$

$$\begin{aligned} \mathbf{SO} \quad U_{\mathbf{K}} &= \sum_{j} e^{-i\mathbf{K}\cdot\mathbf{d}_{j}} U_{j\mathbf{K}} = e^{-i\mathbf{K}\cdot\mathbf{d}_{A}} U_{A\mathbf{K}} + e^{+i\mathbf{K}\cdot\mathbf{d}_{A}} U_{B\mathbf{K}} = \\ &= \cos\left(\mathbf{K}\cdot\mathbf{d}_{A}\right) \left(U_{A\mathbf{K}} + U_{B\mathbf{K}}\right) - i\sin\left(\mathbf{K}\cdot\mathbf{d}_{A}\right) \left(U_{B\mathbf{K}} - U_{A\mathbf{K}}\right) \end{aligned}$$

if the atoms are identical

$$U_{\mathbf{K}} = \sum_{j} e^{-i\mathbf{K}\cdot\mathbf{d}_{j}} U_{j\mathbf{K}} = e^{-i\mathbf{K}\cdot\mathbf{d}_{A}} U_{A\mathbf{K}} + e^{+i\mathbf{K}\cdot\mathbf{d}_{A}} U_{B\mathbf{K}} = U_{\mathbf{K}} = 2\cos\left(\mathbf{K}\cdot\mathbf{d}_{A}\right) U_{A\mathbf{K}}$$

Form factors

$$U_{j\mathbf{K}} = \int d\mathbf{r} U_{j}(\mathbf{r}) e^{-i\mathbf{K}\cdot\mathbf{r}}$$

Assume central potential

unit cell

$$U_{j\mathbf{K}} = \iint_{j\mathbf{K}} d\mathbf{r} U_{j}(r) e^{-i\mathbf{K}\cdot\mathbf{r}} = \iiint d\varphi \, d\theta \, drr^{2} \sin \theta U_{j}(r) e^{-iKr\cos\theta}$$

unit cen

$$=2\pi\int dr r^2 U_j(r) \int_0^{\pi} d\theta \sin \theta e^{-iKr\cos\theta} = 2\pi\int dr r^2 U_j(r) \int_{-1}^1 du e^{-iKru}$$

$$= 2\pi \int dr r^2 U_{j}(r) \frac{e^{-iKru}}{-iKr} \bigg|_{-1}^{1} = 2\pi \int dr r^2 U_{j}(r) \frac{e^{-iKr} - e^{iKr}}{-iKr} =$$

 $=4\pi \int dr r^2 U_j(r) \frac{\sin Kr}{Kr}$

Depends only on magnitude of K

Ranking of reciprocal lattice vectors by magnitude

$$\begin{split} & \boldsymbol{b}_{1}, \boldsymbol{b}_{2}, \boldsymbol{b}_{3}, -\boldsymbol{b}_{1}, -\boldsymbol{b}_{2}, -\boldsymbol{b}_{3}, \boldsymbol{b}_{1} + \boldsymbol{b}_{2} + \boldsymbol{b}_{3}, -\boldsymbol{b}_{1} - \boldsymbol{b}_{2} - \boldsymbol{b}_{3} \Rightarrow V_{3} \\ & \boldsymbol{b}_{1} + \boldsymbol{b}_{2}, \boldsymbol{b}_{1} + \boldsymbol{b}_{3}, \boldsymbol{b}_{2} + \boldsymbol{b}_{3}, -\boldsymbol{b}_{1} - \boldsymbol{b}_{2}, -\boldsymbol{b}_{1} - \boldsymbol{b}_{3}, -\boldsymbol{b}_{2} - \boldsymbol{b}_{3} \Rightarrow V_{4} \\ & \boldsymbol{b}_{1} - \boldsymbol{b}_{2}, \boldsymbol{b}_{1} - \boldsymbol{b}_{3}, \boldsymbol{b}_{2} - \boldsymbol{b}_{3}, \boldsymbol{b}_{2} - \boldsymbol{b}_{1}, \boldsymbol{b}_{3} - \boldsymbol{b}_{1}, \boldsymbol{b}_{3} - \boldsymbol{b}_{2} \Rightarrow V_{8} \\ & 2\boldsymbol{b}_{1} + \boldsymbol{b}_{2}, 2\boldsymbol{b}_{2} + \boldsymbol{b}_{3}, 2\boldsymbol{b}_{3} + \boldsymbol{b}_{1}, -2\boldsymbol{b}_{1} - \boldsymbol{b}_{2}, \\ & -2\boldsymbol{b}_{2} - \boldsymbol{b}_{3}, -2\boldsymbol{b}_{3} - \boldsymbol{b}_{1} \Rightarrow V_{11} \end{split}$$

Diamond structure factors for
$$\mathbf{b}_1$$

 $\cos(\mathbf{K} \cdot \mathbf{d}_A) = \cos\left[-\frac{1}{8}\left(K_x + K_y + K_z\right)a\right]$
 $\cos(\mathbf{b}_1 \cdot \mathbf{d}_A) = \cos\left[-\frac{1}{8}\left(-\frac{2\pi}{a}\right)a\right] = \cos\left[\frac{\pi}{4}\right] = \sqrt{2}/2$
Same for $\mathbf{b}_1 \cdot \mathbf{b}_2 - \mathbf{b}_3 - \mathbf{b}_4$

$$\cos\left(\left(\boldsymbol{b}_{1}+\boldsymbol{b}_{2}+\boldsymbol{b}_{3}\right)\cdot\boldsymbol{d}_{A}\right)=\cos\left[-\frac{1}{8}\left(-\frac{6\pi}{a}\right)a\right]=\cos\left[\frac{3\pi}{4}\right]=-\sqrt{2}/2$$

Same for $- oldsymbol{b}_1 - oldsymbol{b}_2 - oldsymbol{b}_3$

Diamond structure factors for $\mathbf{b}_1 + \mathbf{b}_2$ $\cos(\mathbf{K} \cdot \mathbf{d}_A) = \cos\left[-\frac{1}{8}\left(K_x + K_y + K_z\right)a\right]$ $\cos\left(\left(\mathbf{b}_1 + \mathbf{b}_2\right) \cdot \mathbf{d}_A\right) = \cos\left[-\frac{1}{8}\left(-\frac{4\pi}{a}\right)a\right] = \cos\left[\frac{\pi}{2}\right] = 0$

Same for all other combinations of the form (2,0,0)

Form factors



Spin

Electrons have spin with eigenvalues ½ and ½, and two component eigenfunctions in spin-space of the form

$$\chi_{_{1\!/2}}\equiv\chi_{_{\uparrow}}=\left(\begin{array}{c}1\\0\end{array}\right)\!\!;\quad\chi_{_{-1\!/2}}\equiv\chi_{_{\downarrow}}=\left(\begin{array}{c}0\\1\end{array}\right)$$

Therefore, the complete wavefunction for an electron must be a two-component spinor of the form

$$\left(egin{array}{c} arphiig(m{r},\uparrowig) \ arphiig(m{r},\downarrowig) \end{array}
ight)$$

Hamiltonian

 Any hermitian matrix in spinor space must be a linear combination of Pauli spin matrices

 A hamiltonian must be invariant under rotations, so it must be of the form

$$Hig(m{r},m{s}ig) = H_{_0}ig(m{r}ig)igg(egin{array}{ccc} 1 & 0 \ 0 & 1 \ \end{array}igg) + H_{_x}ig(m{r}ig)igg(egin{array}{ccc} 0 & 1 \ 1 & 0 \ \end{array}igg) + H_{_y}ig(m{r}ig)igg(egin{array}{ccc} 0 & i \ i & 0 \ \end{array}igg) + H_{_z}ig(m{r}ig)igg(egin{array}{ccc} 1 & 0 \ 0 & -1 \ \end{array}igg);$$

Spin-independent hamiltonian

- If the hamiltonian is independent of spin $H(\mathbf{r}, \mathbf{s})\varphi_{\lambda}(\mathbf{r}, \mathbf{s}) =$ $= H_{0}(\mathbf{r}) \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \varphi_{\lambda}(\mathbf{r}, \uparrow) \\ \varphi_{\lambda}(\mathbf{r}, \downarrow) \end{pmatrix} = \begin{pmatrix} H_{0}(\mathbf{r}) & 0 \\ 0 & H_{0}(\mathbf{r}) \end{pmatrix} \begin{pmatrix} \varphi_{\lambda}(\mathbf{r}, \uparrow) \\ \varphi_{\lambda}(\mathbf{r}, \downarrow) \end{pmatrix} = E_{\lambda} \begin{pmatrix} \varphi_{\lambda}(\mathbf{r}, \uparrow) \\ \varphi_{\lambda}(\mathbf{r}, \downarrow) \end{pmatrix}$ • Let $H_{0}\varphi_{\nu}(\mathbf{r}) = E_{\nu}\varphi_{\nu}(\mathbf{r})$
 - Then I can choose as the solutions

$$\left(\begin{array}{c} \varphi_{\lambda} \left(\boldsymbol{r}, \uparrow \right) \\ \varphi_{\lambda} \left(\boldsymbol{r}, \downarrow \right) \end{array} \right) = \varphi_{\nu} \left(\boldsymbol{r} \right) \left(\begin{array}{c} 1 \\ 0 \end{array} \right) \equiv \varphi_{\nu} \left(\boldsymbol{r} \right) \uparrow; \quad \left(\begin{array}{c} \varphi_{\lambda} \left(\boldsymbol{r}, \uparrow \right) \\ \varphi_{\lambda} \left(\boldsymbol{r}, \downarrow \right) \end{array} \right) = \varphi_{\nu} \left(\boldsymbol{r} \right) \left(\begin{array}{c} 0 \\ 1 \end{array} \right) \equiv \varphi_{\nu} \left(\boldsymbol{r} \right) \downarrow$$

Spin-dependent hamiltonian

• If the hamiltonian is spin-dependent, it will be of the form

$$\begin{array}{ccc} H_{_0} + H_{_z} & H_{_x} + iH_{_y} \\ H_{_x} - iH_{_y} & H_{_0} - H_{_z} \end{array} \end{array}$$

 If the off-diagonal terms are not zero, then the spinor wave functions will mix up- and down spins.

Origin of spin

- En mecánica cuántica $H \rightarrow i\hbar \frac{\partial}{\partial t}; p \rightarrow -i\hbar \nabla$
- Entonces, $H = \frac{p^2}{2m} \Rightarrow i\hbar \frac{\partial \Psi}{\partial t} = -\frac{\hbar^2}{2m} \Psi$
- Pero la energía relativista es $H = \sqrt{c^2 p^2 + m_0^2 c^4}$
- If we square to eliminate radical

$$\begin{split} H^{2} &= c^{2}p^{2} + m_{0}^{2}c^{4} \Rightarrow -\hbar^{2}\frac{\partial^{2}\Psi}{\partial t^{2}} = -c^{2}\hbar^{2}\frac{\partial^{2}\Psi}{\partial x^{2}} + m_{0}^{2}c^{4}\Psi\\ &\frac{1}{c^{2}}\frac{\partial^{2}\Psi}{\partial t^{2}} = \hbar^{2}\frac{\partial^{2}\Psi}{\partial x^{2}} - \frac{m_{0}^{2}c^{2}}{\hbar^{2}}\Psi \end{split}$$

 This is the Klein-Gordon equation. It is not an evolution equation. It would imply different postulates for relativistic quantum mechanics.

Dirac equation We propose $\left[c \boldsymbol{\alpha} \cdot \boldsymbol{p} + \boldsymbol{\beta} m_0 c^2\right] \Psi = i\hbar \frac{\partial \Psi}{\partial t}$ And we demand: $\left[c \boldsymbol{\alpha} \cdot \boldsymbol{p} + \boldsymbol{\beta} m_0 c^2\right] \left[c \boldsymbol{\alpha} \cdot \boldsymbol{p} + \boldsymbol{\beta} m_0 c^2\right] = c^2 p^2 + m_0^2 c^4$

This requires

$$\alpha_x^2 = \alpha_y^2 = \alpha_z^2 = \beta^2 = 1$$

$$\alpha_x \alpha_y + \alpha_y \alpha_x = \alpha_y \alpha_z + \alpha_z \alpha_y = \alpha_x \alpha_z + \alpha_z \alpha_x = \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z = \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z = \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z = \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z = \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z + \alpha_z \alpha_z = \alpha_z \alpha_z + \alpha_z \alpha_z = \alpha_z \alpha_z + \alpha_z$$

$$= \alpha_x \beta + \beta \alpha_x = \alpha_y \beta + \beta \alpha_y = \alpha_z \beta + \beta \alpha_z = 0$$

This can only be satisfied if the α 's and β are 4x4 matrices.

Dirac equation $\begin{bmatrix} c \mathbf{\alpha} \cdot \mathbf{p} + \mathbf{\beta} m_0 c^2 \end{bmatrix} \Psi = i\hbar \frac{\partial \Psi}{\partial t}$ $\mathbf{\alpha} = \begin{pmatrix} \mathbf{0} & \mathbf{\sigma} \\ \mathbf{\sigma} & \mathbf{0} \end{pmatrix}; \quad \mathbf{\beta} = \begin{pmatrix} \mathbf{I} & \mathbf{0} \\ \mathbf{0} & -\mathbf{I} \end{pmatrix}$

Thus the wave function is a four-component vector that contains the electron with spin up and down, and the positron with spin up and down. Expansion of Dirac equation in series of v/c gives non-relativistic Schrödinger equation plus other terms, including spin-orbit interaction.

Magnetic moment

 The magnetic moment of a loop current is defined as mu = IA. Applying this to an electron orbiting a nucleus:

$$\mu = \frac{(-e)v}{2\pi r} (\pi r^2) = -\frac{evr}{2}$$
$$= -\frac{emvr}{2m} = -\frac{eL}{2m}$$
$$\mu = -\frac{eL}{2m}$$

Spin

• We might expect to have a magnetic moment associated with the electron spin given by

$$\boldsymbol{\mu} = -\frac{e\boldsymbol{S}}{2m}$$

• but the actual expression is

$$oldsymbol{\mu} = -g_s rac{eoldsymbol{S}}{2m}$$

• Here g_s is the so-called Landé g-factor. From the Dirac equation it is $g_s = 2$, but from QED it is $g_s = 2.0023$

Electron rest frame

• Let us consider an inertial reference frame in which the electron is instantaneously at rest



En este sistema, existe un campo magnético en la posición del electrón debido al movimiento del núcleo hacia la izquierda.

B in electron rest frame

• From Biot-Savart's law



Torque

• Because of the field *B'*, there is a torque on the spin, so that

$$\frac{ds}{dt} = \frac{\mathbf{\mu} \times \mathbf{B}'}{c}$$

• Classically ds/dt is the same whether computed in the lab frame (proton) or in the frame where the electron is instantaneously at rest. But relativistically this is not true because the sytems are rotating relative to each other...

Thomas precession (I)



Assume object flying in a circle. Approximate large circular orbit by N-side polygon. N very large. For each segment, angle changes by $2\pi/N \sim A/B$. But in rest frame of object, B is contracted by γ , so angle is $\gamma A/B$. After circle, angle measured in lab frame is obviously 2π , but angle accumulated on rest frames is $\gamma 2\pi$. Therefore

$$\begin{split} \Delta \theta &= 2\pi \Big(\gamma - 1 \Big) \\ \omega_{_{P}} &= \omega \Big(\gamma - 1 \Big) \end{split}$$

Dividing by T

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}}$$

Rotation sign

For $\theta'' > \theta$, double-primed system is rotated clockwise with respect to unprimed system



Thomas precession 3D

We want to eliminate the angular velocity from our expression, hoping that it will generalize to general, non-circular motion

$$\boldsymbol{\omega}_{P} = \boldsymbol{\omega} \times \boldsymbol{r} \Rightarrow \frac{d\boldsymbol{v}}{dt} = \boldsymbol{\omega} \times \boldsymbol{v}$$

$$\boldsymbol{v} \times \frac{d\boldsymbol{v}}{dt} = \boldsymbol{v} \times (\boldsymbol{\omega} \times \boldsymbol{v}) = \boldsymbol{\omega} (\boldsymbol{v} \cdot \boldsymbol{v}) - \boldsymbol{v} (\boldsymbol{v} \cdot \boldsymbol{\omega}) = v^{2} \boldsymbol{\omega}$$

$$\boldsymbol{\omega}_{P} = \boldsymbol{\omega} (\gamma - 1) \sim \frac{1}{2} \left(\frac{v}{c}\right)^{2} \boldsymbol{\omega}$$

$$\boldsymbol{\omega}_{P} = -\frac{1}{2c^{2}} \boldsymbol{v} \times \frac{d\boldsymbol{v}}{dt}$$







Hydrogenic wave functions

$$\begin{split} \left|1,0,0\right\rangle &= \left|1s\right\rangle = \frac{1}{\sqrt{\pi}} \left(\frac{Z}{a_0}\right)^{3/2} e^{-Zr/a_0} \\ \left|2,0,0\right\rangle &= \left|2s\right\rangle = \frac{1}{4\sqrt{2\pi}} \left(\frac{Z}{a_0}\right)^{3/2} \left(2 - \frac{Zr}{a_0}\right) e^{-Zr/2a_0} \\ \left|2,1,0\right\rangle &= \left|2p_0\right\rangle = \frac{1}{4\sqrt{2\pi}} \left(\frac{Z}{a_0}\right)^{3/2} \frac{Z}{a_0} e^{-Zr/2a_0} r\cos\theta \propto \left|2p_z\right\rangle \\ \left|2,1,1\right\rangle &= \left|2p_1\right\rangle = \frac{1}{8\sqrt{\pi}} \left(\frac{Z}{a_0}\right)^{3/2} \frac{Z}{a_0} e^{-Zr/2a_0} r\sin\theta e^{i\phi} = \frac{\left|2p_x\right\rangle + i\left|2p_y\right\rangle}{\sqrt{2}} \\ \left|2,1,-1\right\rangle &= \left|2p_{-1}\right\rangle = \frac{1}{8\sqrt{\pi}} \left(\frac{Z}{a_0}\right)^{3/2} \frac{Z}{a_0} e^{-Zr/2a_0} r\sin\theta e^{-i\phi} = \frac{\left|2p_x\right\rangle - i\left|2p_y\right\rangle}{\sqrt{2}} \end{split}$$

New notation for p-states



Spin-orbit Interaction

• Because the radial part is the same for all pfunctions, I can write

$$H_{SO} = \lambda \boldsymbol{L} \cdot \boldsymbol{S} = \lambda \left(J^2 - L^2 - S^2 \right) / 2; \quad \boldsymbol{J} = \boldsymbol{L} + \boldsymbol{S}$$

 Accordingly, the SO interaction is diagonalized by simultaneous eigenfunctions of J², L², and S².



Transformation matrix

	$X\uparrow$	$Y\uparrow$	$Z\downarrow$	$X\downarrow$	$Y\downarrow$	$Z\uparrow$
$rac{3}{2},rac{3}{2}$	$1/\sqrt{2}$	$i/\sqrt{2}$	0	0	0	0
$rac{3}{2},-rac{1}{2}$	$1/\sqrt{6}$	$-i/\sqrt{6}$	$\sqrt{2/3}$	0	0	0
$rac{1}{2},-rac{1}{2}$	$-\sqrt{1/3}$	$i\sqrt{1/3}$	$\sqrt{1/3}$	0	0	0
$rac{3}{2},-rac{3}{2}$	0	0	0	$1/\sqrt{2}$	$-i/\sqrt{2}$	0
$rac{3}{2},rac{1}{2}$	0	0	0	$1/\sqrt{6}$	$i/\sqrt{6}$	$\sqrt{2/3}$
$rac{1}{2},rac{1}{2}$	0	0	0	$-\sqrt{1/3}$	$-i\sqrt{1/3}$	$1/\sqrt{3}$

Inverse transformation

 $|X\uparrow\rangle = \frac{1}{\sqrt{2}} |\frac{3}{2}, \frac{3}{2}\rangle + \frac{1}{\sqrt{6}} |\frac{3}{2}, -\frac{1}{2}\rangle - \frac{1}{\sqrt{2}} |\frac{1}{2}, -\frac{1}{2}\rangle$ $\left|Y\uparrow\right\rangle = \frac{-i}{\sqrt{2}}\left|\frac{3}{2},\frac{3}{2}\right\rangle + \frac{i}{\sqrt{6}}\left|\frac{3}{2},-\frac{1}{2}\right\rangle - \frac{i}{\sqrt{3}}\left|\frac{1}{2},-\frac{1}{2}\right\rangle$ $\left| Z \downarrow \right\rangle = \sqrt{\frac{2}{3}} \left| \frac{3}{2}, -\frac{1}{2} \right\rangle + \frac{1}{\sqrt{3}} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle$ $|X\downarrow\rangle = \frac{1}{\sqrt{2}} |\frac{3}{2}, -\frac{3}{2}\rangle + \frac{1}{\sqrt{6}} |\frac{3}{2}, \frac{1}{2}\rangle - \frac{1}{\sqrt{2}} |\frac{1}{2}, \frac{1}{2}\rangle$ $\left|Y\downarrow\right\rangle = \frac{i}{\sqrt{2}} \left|\frac{3}{2}, -\frac{3}{2}\right\rangle - \frac{i}{\sqrt{6}} \left|\frac{3}{2}, \frac{1}{2}\right\rangle + \frac{i}{\sqrt{2}} \left|\frac{1}{2}, \frac{1}{2}\right\rangle$ $\left|Z\uparrow\right\rangle = \sqrt{\frac{2}{3}}\left|\frac{3}{2},\frac{1}{2}\right\rangle + \frac{1}{\sqrt{2}}\left|\frac{1}{2},\frac{1}{2}\right\rangle$

Operator LS

$$\begin{split} J^{2} \left| \frac{3}{2}, \frac{3}{2} \right\rangle &= \frac{15}{4} \left| \frac{3}{2}, \frac{3}{2} \right\rangle; \quad L^{2} \left| \frac{3}{2}, \frac{3}{2} \right\rangle = 2 \left| \frac{3}{2}, \frac{3}{2} \right\rangle; \quad S^{2} \left| \frac{3}{2}, \frac{3}{2} \right\rangle = \frac{3}{4} \left| \frac{3}{2}, \frac{3}{2} \right\rangle \\ J^{2} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle &= \frac{15}{4} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle; \quad L^{2} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle = 2 \left| \frac{3}{2}, \frac{3}{2} \right\rangle; \quad S^{2} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle = \frac{3}{4} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle \\ J^{2} \left| \frac{3}{2}, \frac{1}{2} \right\rangle &= \frac{15}{4} \left| \frac{3}{2}, \frac{1}{2} \right\rangle; \quad L^{2} \left| \frac{3}{2}, \frac{1}{2} \right\rangle = 2 \left| \frac{3}{2}, \frac{1}{2} \right\rangle; \quad S^{2} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle = \frac{3}{4} \left| \frac{3}{2}, -\frac{3}{2} \right\rangle \\ J^{2} \left| \frac{3}{2}, -\frac{1}{2} \right\rangle &= \frac{15}{4} \left| \frac{3}{2}, -\frac{1}{2} \right\rangle; \quad L^{2} \left| \frac{3}{2}, -\frac{1}{2} \right\rangle = 2 \left| \frac{3}{2}, -\frac{1}{2} \right\rangle; \quad S^{2} \left| \frac{3}{2}, -\frac{1}{2} \right\rangle = \frac{3}{4} \left| \frac{3}{2}, -\frac{1}{2} \right\rangle \\ J^{2} \left| \frac{1}{2}, \frac{1}{2} \right\rangle &= \frac{3}{4} \left| \frac{1}{2}, \frac{1}{2} \right\rangle; \quad L^{2} \left| \frac{1}{2}, \frac{1}{2} \right\rangle = 2 \left| \frac{1}{2}, \frac{1}{2} \right\rangle; \quad S^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle = \frac{3}{4} \left| \frac{1}{2}, \frac{1}{2} \right\rangle \\ J^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle &= \frac{3}{4} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle; \quad L^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle = 2 \left| \frac{1}{2}, -\frac{1}{2} \right\rangle; \quad S^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle = \frac{3}{4} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle \\ J^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle &= \frac{3}{4} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle; \quad L^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle = 2 \left| \frac{1}{2}, -\frac{1}{2} \right\rangle; \quad S^{2} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle = \frac{3}{4} \left| \frac{1}{2}, -\frac{1}{2} \right\rangle \\ \end{bmatrix}$$

$$\frac{1}{2} \left(J^2 - L^2 - S^2 \right) \left| \frac{3}{2}, \dots \right\rangle = \frac{1}{2} \left(\frac{15}{4} - 2 - \frac{3}{4} \right) \left| \frac{3}{2}, \dots \right\rangle = \frac{1}{2} \left| \frac{3}{2}, \dots \right\rangle$$
$$\frac{1}{2} \left(J^2 - L^2 - S^2 \right) \left| \frac{1}{2}, \dots \right\rangle = \frac{1}{2} \left(\frac{3}{4} - 2 - \frac{3}{4} \right) \left| \frac{3}{2}, \dots \right\rangle = - \left| \frac{3}{2}, \dots \right\rangle$$

Matrix elements of H_{SO}

$$\begin{split} &\left< \frac{3}{2}, \frac{3}{2} \right| H_{SO} \left| \frac{3}{2}, \frac{3}{2} \right> = \lambda/2 \\ &\left< \frac{3}{2}, \frac{3}{2} \right| H_{SO} \left| \frac{3}{2}, \frac{3}{2} \right> = \lambda/2 \\ &\left< \frac{1}{2}, \frac{3}{2} \right| H_{SO} \left| \frac{3}{2}, \frac{1}{2} \right> = \lambda/2 \\ &\left< -\frac{1}{2}, \frac{3}{2} \right| H_{SO} \left| \frac{3}{2}, -\frac{1}{2} \right> = \lambda/2 \\ &\left< \frac{1}{2}, \frac{1}{2} \right| H_{SO} \left| \frac{1}{2}, \frac{1}{2} \right> = -\lambda \\ &\left< \frac{1}{2}, -\frac{1}{2} \right| H_{SO} \left| \frac{1}{2}, -\frac{1}{2} \right> = -\lambda \end{split}$$

$$\begin{split} \mathsf{H}_{\mathsf{SO}} \ \mathsf{matrix} \ \mathsf{elements} \ \mathsf{of} \ \mathsf{p}\text{-states} \\ \left\langle X \uparrow \left| H_{_{SO}} \right| Y \uparrow \right\rangle = \\ &= -\frac{i}{2} \left\langle \frac{3}{2}, \frac{3}{2} \right| H_{_{SO}} \left| \frac{3}{2}, \frac{3}{2} \right\rangle + \frac{i}{6} \left\langle \frac{-1}{2}, \frac{3}{2} \right| H_{_{SO}} \left| \frac{3}{2}, \frac{-1}{2} \right\rangle + \frac{i}{3} \left\langle \frac{-1}{2}, \frac{1}{2} \right| H_{_{SO}} \left| \frac{1}{2}, \frac{-1}{2} \right\rangle \\ &= -\frac{i}{2} \left(\frac{\lambda}{2} \right) + \frac{i}{6} \left(\frac{\lambda}{2} \right) + \frac{i}{3} \left(-\lambda \right) = -i \left(\frac{\lambda}{2} \right) \\ \left\langle X \uparrow \left| H_{_{SO}} \right| Z \uparrow \right\rangle = 0; \quad \left\langle X \uparrow \left| H_{_{SO}} \right| X \downarrow \right\rangle = 0; \quad \left\langle X \uparrow \left| H_{_{SO}} \right| Y \downarrow \right\rangle = 0 \\ \left\langle X \uparrow \left| H_{_{SO}} \right| Z \downarrow \right\rangle = \lambda/2; \left\langle Y \uparrow \left| H_{_{SO}} \right| Z \downarrow \right\rangle = -i\lambda/2; \left\langle Y \uparrow \left| H_{_{SO}} \right| X \downarrow \right\rangle = 0 \\ \left\langle Y \uparrow \left| H_{_{SO}} \right| Y \downarrow \right\rangle = 0; \quad \left\langle Y \uparrow \left| H_{_{SO}} \right| Z \uparrow \right\rangle = 0; \quad \left\langle Z \downarrow \left| H_{_{SO}} \right| X \downarrow \right\rangle = 0 \\ \left\langle Z \downarrow \left| H_{_{SO}} \right| Y \downarrow \right\rangle = 0; \quad \left\langle Z \downarrow \left| H_{_{SO}} \right| Z \uparrow \right\rangle = 0; \quad \left\langle X \downarrow \left| H_{_{SO}} \right| Y \downarrow \right\rangle = i\lambda/2 \\ \left\langle X \downarrow \left| H_{_{SO}} \right| Z \uparrow \right\rangle = \lambda/2; \quad \left\langle Y \downarrow \left| H_{_{SO}} \right| Z \uparrow \right\rangle = i\lambda/2 \end{split}$$

16x16 matrix

- If we use the base of s and p functions, the matrix elements we just calculated imply that we need to solve a 16x16 problem.
- However, in the case of diamond-structure materials with inversion symmetry, the states are all double-degenerate, so it would in principle be possible to reduce the problem to a 8x8 matrix by taking appropriate symmetric and antisymmetric combinations.