

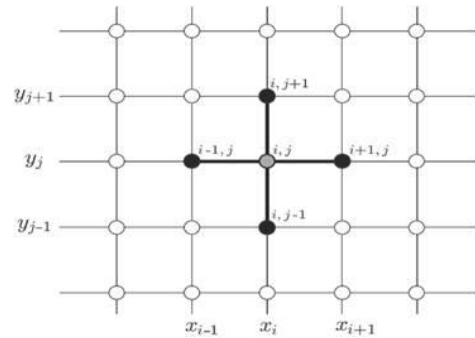
# Métodos numéricos

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Método de Jacobi: 
$$\phi_{i,j}^{n+1} = \frac{1}{4}(\phi_{i+1,j}^n + \phi_{i-1,j}^n + \phi_{i,j+1}^n + \phi_{i,j-1}^n) + \frac{\Delta^2}{4} \rho_{i,j}^n$$

En general, 
$$\mathbf{A} \bar{\mathbf{u}} = \bar{\mathbf{d}}$$



$$\mathbf{A} = \underbrace{\begin{pmatrix} a_{11} & 0 & 0 & 0 & 0 \\ 0 & a_{22} & 0 & 0 & 0 \\ 0 & 0 & a_{33} & 0 & 0 \\ 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & a_{mm} \end{pmatrix}}_{\mathbf{D}} + \underbrace{\begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ a_{21} & 0 & 0 & 0 & 0 \\ a_{31} & a_{32} & 0 & 0 & 0 \\ \dots & \dots & \dots & 0 & 0 \\ a_{m1} & a_{m2} & \dots & a_{m,m-1} & 0 \end{pmatrix}}_{\mathbf{L}} + \underbrace{\begin{pmatrix} 0 & a_{12} & a_{13} & \dots & a_{1m} \\ 0 & 0 & a_{23} & \dots & a_{2m} \\ 0 & 0 & 0 & \dots & \dots \\ 0 & 0 & 0 & 0 & a_{m-1,m} \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}}_{\mathbf{U}}$$

$$\sum_{j=1}^m a_{ij} u_j = d_i \quad ; \quad i = 1, \dots, m$$

$$u_i = \frac{1}{a_{ii}} \left( d_i - \sum_{j=1, j \neq i}^m a_{ij} u_j \right) \quad ; \quad i = 1, \dots, m$$

$$u_i^{n+1} = \frac{1}{a_{ii}} \left( d_i^n - \sum_{j=1, j \neq i}^m a_{ij} u_j^n \right) \quad ; \quad i = 1, \dots, m \quad \text{iteración } n \rightarrow n+1$$

Forma matricial:  $\mathbf{D}\bar{\mathbf{u}}^{n+1} = \bar{\mathbf{d}}^n - (\mathbf{L} + \mathbf{U})\bar{\mathbf{u}}^n \quad \rightarrow \text{Jacobi}$

Se define el residuo  $\bar{\mathbf{R}}^n = \mathbf{A}\bar{\mathbf{u}}^n - \bar{\mathbf{d}}^n = (\mathbf{D} + \mathbf{L} + \mathbf{U})\bar{\mathbf{u}}^n - \bar{\mathbf{d}}^n$

Si llamo  $\Delta\bar{\mathbf{u}}^n = \bar{\mathbf{u}}^{n+1} - \bar{\mathbf{u}}^n \quad \rightarrow \quad \mathbf{D}\Delta\bar{\mathbf{u}}^n = \mathbf{D}\bar{\mathbf{u}}^{n+1} - \mathbf{D}\bar{\mathbf{u}}^n = \bar{\mathbf{d}}^n - (\mathbf{L} + \mathbf{U})\bar{\mathbf{u}}^n - \mathbf{D}\bar{\mathbf{u}}^n$   
 $\rightarrow \quad \mathbf{D}\Delta\bar{\mathbf{u}}^n = -\bar{\mathbf{R}}^n \quad \text{el método "conduce" } \Delta\bar{\mathbf{u}}^n \text{ a } 0$

## Método de Gauss-Seidel (o de relajación)

→ uso valores ya iterados de  $\phi_{i-1,j}^{n+1}$  y  $\phi_{i,j-1}^{n+1}$  para obtener  $\phi_{i,j}^{n+1}$

$$\phi_{i,j}^{n+1} = \frac{1}{4}(\phi_{i+1,j}^n + \phi_{i-1,j}^{n+1} + \phi_{i,j+1}^n + \phi_{i,j-1}^{n+1}) + \frac{\Delta^2}{4}\rho_{i,j}^n$$

→ acelero convergencia

→ se puede ahorrar memoria en un programa (porque no necesito guardar el paso anterior)

Forma general,  $\mathbf{A} \bar{\mathbf{u}} = \bar{\mathbf{d}}$   $\sum_{j=1}^m a_{ij} u_j = d_i \quad ; \quad i = 1, \dots, m$

$$u_i = \frac{1}{a_{ii}} \left( d_i - \sum_{j=1, j \neq i}^m a_{ij} u_j \right) \quad ; \quad i = 1, \dots, m$$

$$u_i^{n+1} = \frac{1}{a_{ii}} \left( d_i^n - \sum_{j=1}^{i-1} a_{ij} u_j^{n+1} - \sum_{j=i+1}^m a_{ij} u_j^n \right) \quad ; \quad i = 1, \dots, m$$

$$\mathbf{D} \bar{\mathbf{u}}^{n+1} + \mathbf{L} \bar{\mathbf{u}}^{n+1} = \bar{\mathbf{d}}^n - \mathbf{U} \bar{\mathbf{u}}^n$$

$$(\mathbf{D} + \mathbf{L}) \bar{\mathbf{u}}^{n+1} = \bar{\mathbf{d}}^n - \mathbf{U} \bar{\mathbf{u}}^n$$

$$(\mathbf{D} + \mathbf{L}) \Delta \bar{\mathbf{u}}^n = \bar{\mathbf{d}}^n - \mathbf{U} \bar{\mathbf{u}}^n - (\mathbf{D} + \mathbf{L}) \bar{\mathbf{u}}^n = \bar{\mathbf{d}}^n - \mathbf{A} \bar{\mathbf{u}}^n = -\bar{\mathbf{R}}^n$$

→ se puede interpretar como otro método que “conduce”  $\Delta \bar{\mathbf{u}}^n$  a 0

## Métodos sobre-relajación

Idea: incrementar la tasa de convergencia “propagando” las correcciones  $\Delta \bar{\mathbf{u}}^n$  más rápido sobre la malla

Si  $\tilde{\mathbf{u}}^{n+1}$  es el valor obtenido en el esquema iterativo básico, el valor siguiente se obtiene cómo:

$$\bar{\mathbf{u}}^{n+1} = w \tilde{\mathbf{u}}^{n+1} + (1 - w) \bar{\mathbf{u}}^n = w (\tilde{\mathbf{u}}^{n+1} - \bar{\mathbf{u}}^n) + \bar{\mathbf{u}}^n$$

$w =$  coeficiente de sobre-relajación

## Jacobi + sobre-relajación

$$\phi_{i,j}^{n+1} = \frac{w}{4} (\phi_{i+1,j}^n + \phi_{i-1,j}^n + \phi_{i,j+1}^n + \phi_{i,j-1}^n + \Delta^2 \rho_{i,j}^n) + (1-w) \phi_{i,j}^n$$

Forma matricial:  $\mathbf{A} \bar{\mathbf{u}} = \bar{\mathbf{d}}$

$$\mathbf{D} \bar{\mathbf{u}}^{n+1} = w \bar{\mathbf{d}}^n - w (\mathbf{L} + \mathbf{U}) \bar{\mathbf{u}}^n + (1-w) \mathbf{D} \bar{\mathbf{u}}^n$$

$$\mathbf{D} \bar{\mathbf{u}}^{n+1} = w (\bar{\mathbf{d}}^n - \mathbf{A} \bar{\mathbf{u}}^n) + \mathbf{D} \bar{\mathbf{u}}^n$$

$$\mathbf{D} \Delta \bar{\mathbf{u}}^n = -w \bar{\mathbf{R}}^n \quad \swarrow -\bar{\mathbf{R}}^n$$

## Gauss-Seidel + sobre-relajación = SOR

(sobre-relajación sucesiva)

$$\tilde{\phi}_{i,j}^{n+1} = \frac{1}{4}(\phi_{i+1,j}^n + \phi_{i-1,j}^{n+1} + \phi_{i,j+1}^n + \phi_{i,j-1}^{n+1}) + \frac{\Delta^2}{4}\rho_{i,j}^n$$

$$\phi_{i,j}^{n+1} = w \tilde{\phi}_{i,j}^{n+1} + (1-w) \phi_{i,j}^n = w(\tilde{\phi}_{i,j}^{n+1} - \phi_{i,j}^n) + \phi_{i,j}^n$$

Forma matricial:  $\mathbf{A} \bar{\mathbf{u}} = \bar{\mathbf{d}}$

$$\mathbf{D} \bar{\mathbf{u}}^{n+1} + w \mathbf{L} \bar{\mathbf{u}}^{n+1} = w \bar{\mathbf{d}}^n - w \mathbf{U} \bar{\mathbf{u}}^n + (1-w) \mathbf{D} \bar{\mathbf{u}}^n$$

$$(\mathbf{D} + w \mathbf{L}) \Delta \bar{\mathbf{u}}^n = -w \bar{\mathbf{R}}^n$$

Cómo elegimos  $w$  ?



## Convergencia de esquemas iterativos

$$\text{Sup. } \bar{\mathbf{u}}_e \text{ sol. exacta de } \mathbf{A} \bar{\mathbf{u}} = \bar{\mathbf{d}} \iff \mathbf{A} \bar{\mathbf{u}}_e = \bar{\mathbf{d}}$$

$$\rightarrow \text{definimos el error en la iteraci3n } n \text{ como } \bar{\boldsymbol{\epsilon}}^n = \bar{\mathbf{u}}^n - \bar{\mathbf{u}}_e$$

$$\text{sup. una subdivisi3n (splitting) arbitraria de } \mathbf{A} = \mathbf{P} + \mathbf{S}$$

$$\text{y un esquema iterativo } \mathbf{P} \bar{\mathbf{u}}^{n+1} = \mathbf{d} - \mathbf{S} \bar{\mathbf{u}}^n \iff \mathbf{P} \Delta \bar{\mathbf{u}}^n = -\bar{\mathbf{R}}^n = \bar{\mathbf{d}}^n - \mathbf{A} \bar{\mathbf{u}}^n$$

$\mathbf{P}$  = matriz de convergencia o pre-condicionador

$\rightarrow$  la elegimos de manera que sea f3cil de invertir y “parecida” a  $\mathbf{A}$

$$\text{Notemos que } \mathbf{P} \bar{\boldsymbol{\epsilon}}^{n+1} = \mathbf{P} \bar{\mathbf{u}}^{n+1} - \mathbf{P} \bar{\mathbf{u}}_e = \bar{\mathbf{d}}^n - \mathbf{S} \bar{\mathbf{u}}^n - \mathbf{P} \bar{\mathbf{u}}_e = -\mathbf{S} \bar{\boldsymbol{\epsilon}}^n$$

$$\text{ya que } \mathbf{A} \bar{\mathbf{u}}_e = (\mathbf{P} + \mathbf{S}) \bar{\mathbf{u}}_e = \bar{\mathbf{d}} \Rightarrow \mathbf{P} \bar{\mathbf{u}}_e = \bar{\mathbf{d}} - \mathbf{S} \bar{\mathbf{u}}_e$$

$$\Rightarrow \bar{\boldsymbol{\epsilon}}^{n+1} = -\mathbf{P}^{-1} \mathbf{S} \bar{\boldsymbol{\epsilon}}^n = (\mathbf{I} - \mathbf{P}^{-1} \mathbf{A}) \bar{\boldsymbol{\epsilon}}^n = (\mathbf{I} - \mathbf{P}^{-1} \mathbf{A})^n \bar{\boldsymbol{\epsilon}}^1$$

$$\mathbf{P}^{-1} \mathbf{A} = \mathbf{I} + \mathbf{P}^{-1} \mathbf{S}$$



$$\mathbf{G} = \mathbf{I} - \mathbf{P}^{-1}\mathbf{A} \quad \rightarrow \text{depende de } \mathbf{P}$$

$$\text{Jacobi: } \mathbf{D} \bar{\mathbf{u}}^{n+1} = \mathbf{d} - (\mathbf{L} + \mathbf{U}) \bar{\mathbf{u}}^n \quad \rightarrow \mathbf{P} = \mathbf{D}, \mathbf{S} = \mathbf{L} + \mathbf{U} \quad \mathbf{G} = \mathbf{I} - \mathbf{D}^{-1}(\mathbf{D} + \mathbf{L} + \mathbf{U}) = -\mathbf{D}^{-1}(\mathbf{L} + \mathbf{U})$$

$$\text{Gauss-Seidel: } (\mathbf{D} + \mathbf{L}) \bar{\mathbf{u}}^{n+1} = \mathbf{d} - \mathbf{U} \bar{\mathbf{u}}^n \quad \rightarrow \mathbf{P} = \mathbf{D} + \mathbf{L}, \mathbf{S} = \mathbf{U} \quad \mathbf{G} = \mathbf{I} - (\mathbf{D} + \mathbf{L})^{-1}(\mathbf{D} + \mathbf{L} + \mathbf{U}) = -(\mathbf{D} + \mathbf{L})^{-1}\mathbf{U}$$

$\rightarrow$  se puede ver que convergen si  $\mathbf{A}$  es “*dominante diagonal*”

tasa de reducción de error  $\Delta\epsilon^n = \left[ \frac{|\epsilon^n|}{|\epsilon^1|} \right]^{1/n}$

$$\text{Cómo } \epsilon^n = (\mathbf{G})^n \epsilon^1 \Rightarrow \Delta\epsilon^n \leq \sigma(\mathbf{G})$$

$$S = \text{tasa de convergencia} = |\log \sigma(\mathbf{G})|$$

El error se reduce un factor 10 en un número de iteraciones  $n$  tal que

$$\left(\frac{1}{10}\right)^{1/n} \geq \sigma(G) \rightarrow 10^{-1/n} \geq \sigma(G) \rightarrow -\frac{1}{n} \geq \log \sigma \rightarrow -\log \sigma \geq \frac{1}{n} \rightarrow n \geq -\frac{1}{\log \sigma}$$

Ejemplo: ec. Poisson + met. Jacobi, c.c. periódicas

$$\mathbf{A} = \begin{pmatrix} -4 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 1 & -4 & 1 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & -4 & 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & -4 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 1 & -4 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & -4 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & -4 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & -4 & 1 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 & -4 \end{pmatrix}$$

Se puede ver que  $\sin\left(\frac{\pi l i}{M}\right) \sin\left(\frac{\pi m j}{M}\right)$  son autofunciones de  $\mathbf{A}$ , con autovalor

$$\Omega = -4 \left[ \sin^2\left(\frac{\pi l i}{2M}\right) + \sin^2\left(\frac{\pi m j}{2M}\right) \right] \quad l, m = 1, \dots, M$$

Como  $\mathbf{G} = \mathbf{I} - \mathbf{P}^{-1}\mathbf{A} \rightarrow \lambda = 1 - \frac{\Omega}{d}$  son autovalores de  $\mathbf{G}$

$$\lambda = 1 - \left[ \sin^2 \left( \frac{\pi l i}{2M} \right) + \sin^2 \left( \frac{\pi m j}{2M} \right) \right] = \frac{1}{2} \left[ \cos \left( \frac{\pi l}{M} \right) + \cos \left( \frac{\pi m}{M} \right) \right]$$

el autovalor más grande es  $\sigma = \cos \frac{\pi}{M} < 1$

$$\text{Si } M \gg 1 \rightarrow \sigma \simeq 1 - \frac{\pi^2}{2M^2}$$

Para  $M = 100 \rightarrow \sigma = 0.9995$ ,  $\log \sigma = -0.0002$   $-1/\log \sigma \simeq 4600$

Reduzco el error un factor 10 en 4600 iteraciones

para Gauss-Seidel,  $\mathbf{G} = \mathbf{I} - (\mathbf{D} + \mathbf{L})^{-1} \mathbf{A}$

$$\text{y se puede ver que } \lambda = \frac{1}{4} \left[ \cos \left( \frac{\pi l}{M} \right) + \cos \left( \frac{\pi m}{M} \right) \right]^2$$

$$\text{y el valor máximo es } \sigma = \cos^2 \frac{\pi}{M} \simeq 1 - \frac{\pi^2}{M^2}, \quad M \gg 1$$

→ converge más rápido que Jacobi

Para  $M = 100 \rightarrow -1/\log \sigma \simeq 2331$

Para el método SOR vimos que  $(\mathbf{D} + w \mathbf{L}) \Delta \bar{\mathbf{u}}^n = -w \bar{\mathbf{R}}^n$

y de la definición de  $\bar{\boldsymbol{\epsilon}}^n = \bar{\mathbf{u}}^n - \bar{\mathbf{u}}_e$      $\mathbf{A} \bar{\mathbf{u}}_e = \bar{\mathbf{d}}$

se obtiene,  $\bar{\boldsymbol{\epsilon}}^{n+1} = \mathbf{G} \bar{\boldsymbol{\epsilon}}^n$      $\mathbf{G} = (\mathbf{D} + w \mathbf{L})^{-1}[(1-w)\mathbf{D} - w\mathbf{U}]$

es difícil sacar los autovalores de G pero se puede usar que  $\det(\mathbf{G}) = \prod_{j=1}^M \lambda_j$

$$\text{Si } \det(\mathbf{G})^M \leq 1 \Rightarrow \sigma(\mathbf{G}) \leq 1$$

usando que son matrices triangulares se puede ver que  $\det(\mathbf{G}) = (1-w)^M$

$$\rightarrow \sigma^M \geq (1-w)^M \Rightarrow |1-w| \leq \sigma < 1 \Rightarrow 0 < w < 2$$

Existe un valor  $w_{opt}$  que minimiza  $\sigma(G)$

$$\rightarrow w_{opt} = \frac{2}{1 + \sqrt{1 - \sigma_J^2}} \quad \text{y en ese caso } \sigma(w_{opt}) = w_{opt} - 1$$

$\sigma_J$  = máximo autovalor c/ met. Jacobi

Para el problema de Poisson sabemos que  $\sigma_J = \cos \frac{\pi}{M}$

$$\rightarrow w_{opt} = \frac{2}{1 + \sin \frac{\pi}{M}} \simeq 2 \left( 1 - \frac{\pi}{M} + \frac{\pi^2}{M^2} \right), \quad M \gg 1$$

$$\rightarrow \sigma_{SOR} \simeq 1 - \frac{2\pi}{M} + O\left(\frac{1}{M^2}\right)$$

que es mucho más chico que el sigma de Gauss-Seidel o Jacobi

$$\text{Para } M = 100 \rightarrow -1/\log \sigma \simeq 35 \quad !!$$

Otros métodos iterativos  $\rightarrow$  [Gradiente Conjugado](#) y [GMRES](#)

 CGM

Generalized Minimal Residual Method

Para matrices simétricas y def.  
positiva.  
Des. en 1952, Hestenes & Stiefel

Matrices no simétricas.  
Des. en 1986, Saad & Schultz